## 1 Last time: row reduction to (reduced) echelon form

The leading entry in a nonzero row of a matrix is the first nonzero entry from left going right. For example, the row $\left[\begin{array}{lllll}0 & 0 & 7 & 0 & 5\end{array}\right]$ has leading entry 7 , which occurs in the 3rd column.

Definition. A matrix with $m$ rows and $n$ columns is in echelon form if it has the following properties:

1. If a row is nonzero, then every row above it is also nonzero.
2. The leading entry in a nonzero row is in a column to the right of the leading entry in the row above.
3. If a row is nonzero, then every entry below its leading entry in the same column is zero.

For example,

$$
\left[\begin{array}{llll}
1 & 2 & 0 & 0  \tag{*}\\
0 & 3 & 5 & 0 \\
0 & 0 & 0 & 0
\end{array}\right]
$$

is in echelon form, but none of

$$
\left[\begin{array}{llll}
1 & 2 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 3 & 5 & 0
\end{array}\right] \quad \text { or } \quad\left[\begin{array}{llll}
0 & 2 & 0 & 0 \\
0 & 3 & 5 & 0 \\
0 & 0 & 0 & 0
\end{array}\right] \quad \text { or } \quad\left[\begin{array}{llll}
0 & 2 & 0 & 0 \\
1 & 3 & 5 & 0 \\
0 & 0 & 4 & 5
\end{array}\right]
$$

is in echelon form.
Definition. A matrix is in reduced echelon form if

1. The matrix is in echelon form.
2. Each nonzero row has leading entry 1.
3. The leading 1 in each nonzero row is the only nonzero number in its column.

The matrix

$$
\left[\begin{array}{rrrr}
1 & 0 & -10 / 3 & 0 \\
0 & 1 & 5 / 3 & 0 \\
0 & 0 & 0 & 0
\end{array}\right]
$$

is in reduced echelon form and is row equivalent to the matrix $\left(^{*}\right)$.
Theorem. Each matrix $A$ is row equivalent to exactly one matrix in reduced echelon form, which we denote RREF(A).

The row reduction algorithm is a way of constructing $\operatorname{RREF}(\mathrm{A})$ given $A$. This algorithm is something you should memorize and be able to perform quickly. We won't review the full definition again in this lecture, but let's do an example.

Example. Writing $\rightarrow$ to indicate a sequence of row operations, we have
$\left[\begin{array}{llll}1 & 1 & 1 & 0 \\ 1 & 2 & 4 & 1 \\ 1 & 3 & 9 & 2\end{array}\right] \rightarrow\left[\begin{array}{llll}1 & 1 & 1 & 0 \\ 0 & 1 & 3 & 1 \\ 0 & 2 & 8 & 2\end{array}\right] \rightarrow\left[\begin{array}{llll}1 & 1 & 1 & 0 \\ 0 & 1 & 3 & 1 \\ 0 & 0 & 2 & 0\end{array}\right] \rightarrow\left[\begin{array}{llll}1 & 1 & 1 & 0 \\ 0 & 1 & 3 & 1 \\ 0 & 0 & 1 & 0\end{array}\right] \rightarrow\left[\begin{array}{llll}1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 0\end{array}\right] \rightarrow\left[\begin{array}{rrrr}1 & 0 & 0 & -1 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 0\end{array}\right]$
and the last matrix is the reduced echelon form of the first matrix.
We could actually have figured this out with less work: note that the first matrix is the augmented matrix of the linear system

$$
\begin{aligned}
a+b+c & =0 \\
a+2 b+2^{2} c & =1 \\
a+3 b+3^{2} c & =2
\end{aligned}
$$

where I've used $a, b, c$ as variables rather than $x_{1}, x_{2}, x_{3}$ as usual. Numbers $a, b, c$ satisfying this system are the coefficients of a polynomial $f(x)=a+b x+c x^{2}$ with $f(1)=0, f(2)=1$, and $f(3)=2$, i.e., a quadratic function whose graph is a parabola passing through the points $(x, y)=(1,0),(2,1),(2,2)$. But these three points are all on the line $y=x-1$, so we must have $f(x)=x-1$ and $(a, b, c)=(-1,1,0)$ must be the unique solution to our system. This forces the reduced echelon form of our augmented matrix to be what we computed.

A pivot column of a matrix $A$ is a column containing a leading 1 in $\operatorname{RREF}(\mathrm{A})$.
If $A$ is the augmented matrix of a linear system in variables $x_{1}, x_{2}, \ldots, x_{n}$, then we say that $x_{i}$ is a basic variable if $i$ is a pivot column and that $x_{i}$ is a free variable if $i$ is not a pivot column.

To determine the basic and free variables of the system, we have to perform the row reduction algorithm to figure out what $\operatorname{RREF}(A)$ is first. Once we have this we can conclude that:

- The system has 0 solutions if the last column is a pivot column of $A$.
- The system has $\infty$ solutions if the last column is not a pivot column but there is $\geq 1$ free variable.
- The system has 1 solution if there are no free variables, and the last column is not a pivot column.

Moreover, here's how you find all the solutions to the system: choose any values for the free variables, then solve the basic variables in terms of the free variables via the equations which make up the linear system corresponding to RREF(A).

## 2 Vectors

Until we see vector spaces later in this course, the term vector will always refer to an ordered list of numbers in $\mathbb{R}$. A vector (sometimes to be called a column vector) is such a list oriented vertically; in other words, a matrix with one column:

$$
[1] \quad \text { or } \quad\left[\begin{array}{r}
3 \\
-1
\end{array}\right] \quad \text { or } \quad\left[\begin{array}{l}
1 \\
2 \\
3 \\
5
\end{array}\right] \quad \text { or } \quad\left[\begin{array}{c}
\sqrt{7} \\
\sqrt{6}
\end{array}\right]
$$

We write a general column vector as

$$
v=\left[\begin{array}{r}
v_{1} \\
v_{2} \\
\vdots \\
v_{n}
\end{array}\right]
$$

where each $v_{i}$ is a real number. Two vectors $u$ and $v$ are equal if they have the same number of rows and the same entries in each row.
The sum of two vectors is

$$
\left[\begin{array}{r}
v_{1} \\
v_{2} \\
\vdots \\
v_{n}
\end{array}\right]+\left[\begin{array}{r}
u_{1} \\
u_{2} \\
\vdots \\
u_{n}
\end{array}\right]=\left[\begin{array}{r}
u_{1}+v_{1} \\
u_{2}+v_{2} \\
\vdots \\
u_{n}+v_{n}
\end{array}\right]
$$

Note: $u+v=v+u$, but we can only add together vectors with the same number of rows.
If $v$ is a vector and $c \in \mathbb{R}$ is a scalar, i.e., a real number, then we define

$$
c v=c\left[\begin{array}{r}
v_{1} \\
v_{2} \\
\vdots \\
v_{n}
\end{array}\right]=\left[\begin{array}{r}
c v_{1} \\
c v_{2} \\
\vdots \\
c v_{n}
\end{array}\right]
$$

We call the new vector $c v$ the scalar multiple of $v$ by $c$.
Example. To be concrete, we have

$$
\left[\begin{array}{r}
1 \\
-2
\end{array}\right]+\left[\begin{array}{l}
2 \\
5
\end{array}\right]=\left[\begin{array}{l}
3 \\
3
\end{array}\right]
$$

and

$$
-\left[\begin{array}{r}
1 \\
-2
\end{array}\right]=\left[\begin{array}{r}
-1 \\
2
\end{array}\right]
$$

Define

$$
\left[\begin{array}{r}
1 \\
-2
\end{array}\right]-\left[\begin{array}{l}
2 \\
5
\end{array}\right]=\left[\begin{array}{r}
1 \\
-2
\end{array}\right]+(-1)\left[\begin{array}{l}
2 \\
5
\end{array}\right]=\left[\begin{array}{r}
1 \\
-2
\end{array}\right]+\left[\begin{array}{r}
-1 \\
-5
\end{array}\right]=\left[\begin{array}{r}
0 \\
-7
\end{array}\right]
$$

The dimension of a vector $v$ is the number of its rows. We write $\mathbb{R}^{n}$ for the set of all $n$-dimensional vectors. Vectors in dimension 2, i.e., vectors $a=\left[\begin{array}{l}a_{1} \\ a_{2}\end{array}\right] \in \mathbb{R}^{2}$, can be identified with arrows in the Cartesian plane from the origin the point $(x, y)=\left(a_{1}, a_{2}\right)$ :


Proposition. The sum $a+b$ of two vectors $a, b \in \mathbb{R}^{2}$ is the vector represented by the arrow from the origin to the point which is the opposite vertex of the parallelogram with sides $a$ and $b$ :


Proof. Check that $\frac{a_{2}}{a_{1}}=\frac{\left(a_{2}+b_{u}\right)-b_{2}}{\left(a_{1}+b_{1}-b_{1}\right.}$ and $\frac{b_{2}}{b_{1}}=\frac{\left(a_{2}+b_{2}\right)-a_{2}}{\left(a_{1}+b_{1}\right)-a_{2}}$. Hence the endpoint of $a+b$ is the intersection of the line through the endpoint of $a$ parallel to $b$, and the line through the endpoint of $b$ parallel to $a$.

The zero vector $0 \in \mathbb{R}^{n}$ is the vector

$$
0=\left[\begin{array}{c}
0 \\
0 \\
\vdots \\
0
\end{array}\right]
$$

whose entries are all zero. Note that $0+v=v+0=v$ for any vector $v$.
Definition. Suppose $v_{1}, v_{2}, \ldots, v_{p} \in \mathbb{R}^{n}$ are distinct vectors and $c_{1}, c_{2}, \ldots, c_{p} \in \mathbb{R}$ are scalars, i.e., numbers. The vector $y=c_{1} v_{1}+c_{2} v_{2}+\cdots+c_{p} v_{p}$ is called a linear combination of $v_{1}, v_{2}, \ldots, v_{p}$. It is the linear combination with coefficients $c_{1}, c_{2}, \ldots, c_{p}$.

Example. Suppose $a=\left[\begin{array}{r}1 \\ -2 \\ -5\end{array}\right]$ and $b=\left[\begin{array}{l}2 \\ 5 \\ 6\end{array}\right]$ and $c=\left[\begin{array}{r}7 \\ 4 \\ -3\end{array}\right]$. Is $c$ a linear combination of $a$ and $b$ ?
If it were, we could find numbers $x_{1}, x_{2} \in \mathbb{R}$ such that $x_{1} a+x_{2} b=c$, i.e., such that

$$
\begin{aligned}
x_{1}+2 x_{2} & =7 \\
-2 x_{1}+5 x_{2} & =4 \\
-5 x_{1}+6 x_{2} & =-3 .
\end{aligned}
$$

So to answer our question we need to determine if this linear system has a solution. To do this, use row reduction!

$$
A=\left[\begin{array}{rrr}
1 & 2 & 7 \\
-2 & 5 & 4 \\
-5 & 6 & -3
\end{array}\right] \rightarrow\left[\begin{array}{rrr}
1 & 2 & 7 \\
0 & 9 & 18 \\
0 & 16 & 32
\end{array}\right] \rightarrow\left[\begin{array}{lll}
1 & 2 & 7 \\
0 & 1 & 2 \\
0 & 1 & 2
\end{array}\right] \rightarrow\left[\begin{array}{lll}
1 & 2 & 7 \\
0 & 1 & 2 \\
0 & 0 & 0
\end{array}\right] \rightarrow \operatorname{RREF}(\mathrm{A})=\left[\begin{array}{lll}
1 & 0 & 3 \\
0 & 1 & 2 \\
0 & 0 & 0
\end{array}\right] .
$$

The pivot columns of $A$ are thus 1 and 2: the last column is not a pivot column. Therefore our linear system is consistent, which means that $c$ is a linear combination of $a$ and $b$. (With what coefficients?)
We generalize this example with the following statement.
Proposition. A vector equation of the form $x_{1} a_{1}+x_{2} a_{2}+\cdots+x_{n} a_{n}=b$ where $x_{1}, x_{2}, \ldots, x_{n}$ are variables and $a_{1}, a_{2}, \ldots, a_{n}, b \in \mathbb{R}^{m}$ are vectors, has the same solutions as those for the linear system with augmented matrix

$$
\left[\begin{array}{llllll}
a_{1} & a_{2} & a_{3} & \ldots & a_{n} & b
\end{array}\right]
$$

(This notation means: the matrix whose $i$ th column is $a_{i}$ and last column is $b$.) In particular, $b$ is a linear combination of $a_{1}, a_{2}, \ldots, a_{n}$ if and only if this linear system is consistent.

Definition. The span of a vectors $v_{1}, v_{2}, \ldots, v_{p} \in \mathbb{R}^{n}$ is the set of all vectors $y \in \mathbb{R}^{n}$ which are linear combinations of $v_{1}, v_{2}, \ldots, v_{p}$. We typically denote the span of some set of vectors by

$$
\mathbb{R}-\operatorname{span}\left\{v_{1}, v_{2}, \ldots, v_{p}\right\} \quad \text { or } \quad \operatorname{span}\left\{v_{1}, v_{2}, \ldots, v_{p}\right\}
$$

What does $\mathbb{R}$-span $\left\{v_{1}, v_{2}, \ldots, v_{p}\right\}$ look like?
We can visualize the span of the 0 vector as the single point consisting of just the origin. We imagine the span of a collection of vectors that all belong to the same line through the origin as that line.
In $\mathbb{R}^{2}$, if the span of $v_{1}, v_{2}, \ldots, v_{p}$ does not consist of a line, then the span is the whole plane. To see this, imagine we have two vectors $u, v \in \mathbb{R}^{2}$ which are not parallel. We can then get to any point in the plane by travelling some distance in the $u$ direction, then some distance in the $v$ direction. In other words, we can get any vector in $\mathbb{R}^{2}$ as the linear combination $a u+b v$ for some scalars $a, b \in \mathbb{R}$. Draw a picture to illustrate this to yourself:
(Can you also explain this algebraically, in terms of the reduced echelon form of a matrix like the one in our last example?)

