1 Last time: complex eigenvalues

Write \mathbb{C} for the set of complex numbers $\{a + bi : a, b \in \mathbb{R}\}$.

Each complex number is a formal linear combination of two real numbers a + bi.

The symbol *i* is defined as the square root of -1, so $i^2 = -1$.

We add complex numbers like this:

$$(a+bi) + (c+di) = (a+c) + (b+d)i.$$

We multiply complex numbers just like polynomials, but substituting -1 for i^2 :

$$(a+bi)(c+di) = ac + (ad+bc)i + bd(i^{2}) = (ac-bd) + (ad+bc)i$$

The order of multiplication doesn't matter since (a + bi)(c + di) = (c + di)(a + bi).

Draw $a + bi \in \mathbb{C}$ as the vector $\begin{bmatrix} a \\ b \end{bmatrix} \in \mathbb{R}^2$.

Theorem (Fundamental theorem of algebra). Suppose

$$p(x) = a_n x^n + a_{n-1} x^{n-1} + \dots + a_1 x + a_0$$

is a polynomial of degree n (meaning $a_n \neq 0$) with coefficients $a_0, a_1, \ldots, a_n \in \mathbb{C}$. Then there are n (not necessarily distinct) numbers $r_1, r_2, \ldots, r_n \in \mathbb{C}$ such that

$$p(x) = (-1)^n a_n (r_1 - x) (r_2 - x) \cdots (r_n - x).$$

One calls the numbers r_1, r_2, \ldots, r_n the roots of p(x).

A root r has multiplicity m if exactly m of the numbers r_1, r_2, \ldots, r_n are equal to r.

Define \mathbb{C}^n as the set of vectors with *n*-rows and entries in \mathbb{C} , that is:

$$\mathbb{C}^{n} = \left\{ \begin{bmatrix} v_{1} \\ v_{2} \\ \vdots \\ v_{n} \end{bmatrix} : v_{1}, v_{2}, \dots, v_{n} \in \mathbb{C} \right\}.$$

We have $\mathbb{R}^n \subset \mathbb{C}^n$. The sum u + v and scalar multiple cv for $u, v \in \mathbb{C}^n$ and $c \in \mathbb{C}$ are defined exactly as for vectors in \mathbb{R}^n , except we use the addition and multiplication operations for \mathbb{C} instead of \mathbb{R} . If A is an $n \times n$ matrix and $v \in \mathbb{C}^n$ then we define Av in the same way as when $v \in \mathbb{R}^n$.

Definition. Let A be an $n \times n$ matrix. A number $\lambda \in \mathbb{C}$ a *(complex) eigenvalue* of A if there exists a nonzero vector $v \in \mathbb{C}^n$ such that $Av = \lambda v$, or equivalently if $\det(A - \lambda I) = 0$.

If A is an $n \times n$ matrix then A has n possibly complex and not necessarily distinct eigenvalues, counting repeated eigenvalues with their respective multiplicities.

Given $a, b \in \mathbb{R}$, we define the *complex conjugate* of the complex number $a + bi \in \mathbb{C}$ to be

$$\overline{a+bi} = a - bi \in \mathbb{C}.$$

If A is a matrix and $v \in \mathbb{C}^n$ then we define \overline{A} and \overline{v} as the matrix and vector given by replacing all entries of A and v by their complex conjugates.

Lemma. Let $z \in \mathbb{C}$. Then $\overline{z} = z$ if and only if $z \in \mathbb{R}$.

Lemma. If $y, z \in \mathbb{C}$ then $\overline{y+z} = \overline{y} + \overline{z}$ and $\overline{yz} = \overline{y} \cdot \overline{z}$.

Hence if A is an $m \times n$ matrix (with real or complex entries) and $v \in \mathbb{C}^n$ then $\overline{Av} = \overline{Av}$. If $z = a + bi \in \mathbb{C}$ then $z\overline{z} = (a + bi)(a - bi) = a^2 + b^2 \in \mathbb{R}$.

This indicates how to divide complex numbers:

$$\frac{1}{a+bi} = \frac{a-bi}{(a+bi)(a-bi)} = \frac{a-bi}{a^2+b^2} = \frac{a}{a^2+b^2} - \frac{b}{a^2+b^2}i$$

and more generally

$$\frac{c+di}{a+bi} = \frac{1}{a+bi} \cdot (c+di).$$

Proposition. Suppose A is an $n \times n$ matrix with real entries. If A has a complex eigenvalue $\lambda \in \mathbb{C}$ with eigenvector $v \in \mathbb{C}^n$ then $\overline{v} \in \mathbb{C}^n$ is an eigenvector for A with eigenvalue $\overline{\lambda}$.

The real part of a complex number $a + bi \in \mathbb{C}$ is $\Re(a + bi) = a \in \mathbb{R}$.

The imaginary part of a $a + bi \in \mathbb{C}$ is $\Im(a + bi) = b \in \mathbb{R}$.

Define $\Re(v)$ and $\Im(v)$ for $v \in \mathbb{C}^n$ by applying $\Re(\cdot)$ and $\Im(\cdot)$ to each entry in v.

Theorem. Let A be a real 2×2 matrix with a complex eigenvalue $\lambda = a - bi \ (b \neq 0)$ and associated eigenvector $v \in \mathbb{C}^2$. Then $A = PCP^{-1}$ where

$$P = \begin{bmatrix} \Re(v) & \Im(v) \end{bmatrix}$$
 and $C = \begin{bmatrix} a & -b \\ b & a \end{bmatrix}$.

2 Some final properties of eigenvalues and eigenvectors

Before moving on to to inner products and orthogonality, we prove a few remaining properties of the (complex) eigenvalues and eigenvectors of a matrix which are worth remembering.

Lemma. Suppose we can write a polynomial in x in two ways as

$$(\lambda_1 - x)(\lambda_2 - x)\cdots(\lambda_n - x) = a_n x^n + a_{n-1} x^{n-1} + \dots + a_1 x + a_0$$

for some complex numbers $\lambda_1, \lambda_2, \ldots, \lambda_n, a_0, a_1, \ldots, a_n \in \mathbb{C}$. Then

$$a_n = (-1)^n$$
 and $a_{n-1} = (-1)^{n-1}(\lambda_1 + \lambda_2 + \dots + \lambda_n)$ and $a_0 = \lambda_1 \lambda_2 \cdots \lambda_n$.

Proof. The product $(\lambda_1 - x)(\lambda_2 - x)\cdots(\lambda_n - x)$ is a sum of 2^n monomials corresponding to a choice of either λ_i or -x for each of the *n* factors, multiplied together.

The only such monomial of degree n is $(-x)^n = (-1)^n x^n = a_n x^n$ so $a_n = (-1)^n$.

The only such monomial of degree 0 is $\lambda_1 \lambda_2 \cdots \lambda_n = a_0$.

Finally, there are n monomial which arise of degree n-1:

$$\lambda_1(-x)^{n-1} + (-x)\lambda_2(-x)^{n-2} + (-x)^2\lambda_3(-x)^{n-3} + \dots + (-x)^{n-1}\lambda_n = (-1)^{n-1}(\lambda_1 + \dots + \lambda_n)x^{n-1}$$

This sum must be equal to $a_{n-1}x^{n-1}$ so $a_{n-1} = (-1)^{n-1}(\lambda_1 + \lambda_2 + \dots + \lambda_n)$.

Let A be an $n \times n$ matrix.

Define tr(A) as the sum of the diagonal entries of A. Call tr(A) the *trace* of A.

Example. tr
$$\left(\begin{bmatrix} 1 & 0 & 7 \\ -1 & 2 & 8 \\ 2 & 4 & 3 \end{bmatrix} \right) = 1 + 2 + 3 = 6.$$

Proposition. If A, B are $n \times n$ matrices then tr(A + B) = tr(A) + tr(B) and tr(AB) = tr(BA).

However, usually $tr(AB) \neq tr(A)tr(B)$, unlike for the determinant.

Proof. The diagonal entries of A + B are given by adding together the diagonal entries of A with those of B in corresponding positions, so it follows that tr(A + B) = tr(A) + tr(B).

Let A_{ij} and B_{ij} be the entries of A and B in positions (i, j). Then

$$(AB)_{jj} = \sum_{i=1}^{n} A_{ij}B_{ji}$$
 and $(BA)_{jj} = \sum_{i=1}^{n} B_{ij}A_{ji} = \sum_{i=1}^{n} A_{ji}B_{ij}$

 \mathbf{SO}

$$tr(AB) = \sum_{j=1}^{n} \sum_{i=1}^{n} A_{ij} B_{ji}$$
 and $tr(BA) = \sum_{j=1}^{n} \sum_{i=1}^{n} A_{ji} B_{ij}$.

These sums are equal, since if we swap the roles of i and j in one expression we get the other.

Theorem. Let A be an $n \times n$ matrix (with entries in \mathbb{R} or \mathbb{C}).

Suppose the characteristic polynomial of A factors as

$$\det(A - xI) = (\lambda_1 - x)(\lambda_2 - x)\cdots(\lambda_n - x).$$

Then det $A = \lambda_1 \lambda_2 \cdots \lambda_n$ and tr $A = \lambda_1 + \lambda_2 + \cdots + \lambda_n$. In other words:

- (a) The product of the (complex) eigenvalues of A, counted with multiplicity, is det(A).
- (b) The sum of the (complex) eigenvalues of A, counted with multiplicity if tr(A).

Remark. The noteworthy thing about this theorem is that it is true for all matrices.

For a diagonalisable matrix the result is much easier to prove.

If A = PDP - 1 where D is a diagonal matrix, then

$$\det(A) = \det(PDP^{-1}) = \det(P)\det(D)\det(P)^{-1} = \det(D) = \lambda_1\lambda_2\cdots\lambda_n$$

since $\det(P) \det(P^{-1}) = \det(PP^{-1}) = \det(I) = 1$. Also

$$\operatorname{tr}(A) = \operatorname{tr}(PDP^{-1}) = \operatorname{tr}(DP^{-1}P) = \operatorname{tr}(D) = \lambda_1 + \lambda_2 + \dots + \lambda_n.$$

Before proving the theorem let's see an example.

Example. If we have

$$A = \left[\begin{array}{rrr} 0 & 1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & i \end{array} \right]$$

then $\begin{bmatrix} -i \\ 1 \\ 0 \end{bmatrix}$, $\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$, and $\begin{bmatrix} i \\ 1 \\ 0 \end{bmatrix}$ are eigenvectors of A with eigenvalues i, i, and -i. One can check that

$$\det(A - xI) = -x^3 + ix^2 - x + i = (i - x)^2(-i - x),$$

so the theorem asserts that $(i)(i)(-i) = -i^3 = i = \det(A)$ and $i + i + (-i) = i = \operatorname{tr}(A)$.

Proof of the theorem. We can write $\det(A - xI) = a_n x^n + a_{n-1} x^{n-1} + \dots + a_1 x + a_0$ for some numbers $a_0, a_1, \dots, a_n \in \mathbb{C}$. By the lemma it suffices to show that $a_0 = \det(A)$ and $a_{n-1} = (-1)^{n-1} \operatorname{tr}(A)$.

The first claim is easy. The value of a_0 is given by setting x = 0 in det(A - xI), so $a_0 = det(A)$.

Showing that $a_{n-1} = (-1)^{n-1} \operatorname{tr}(A)$ takes a little more work. Consider the coefficient a_{n-1} of x^{n-1} in the characteristic polynomial $\det(A - xI)$. Remember our formula

$$\det(A - xI) = \sum_{Z \in S_n} (-1)^{\operatorname{inv}(Z)} \Pi(Z, A - xI)$$
(*)

where $\Pi(Z, A - xI)$ is the product of the entries of A - xI in the nonzero positions of the permutation matrix Z. The key observation to make is that if $Z \in S_n$ is not the identity matrix then Z has at most n-2 nonzero entries on the diagonal, so $\Pi(Z, A - xI)$ is a polynomial in x degree at most n-2.

Therefore the formula (*) implies that

$$det(A - xI) = \Pi(I, A - xI) + polynomial terms of degree \le n - 2.$$

Let d_i be the diagonal entry of A in position (i, i). Then $\Pi(I, A - xI) = (d_1 - x)(d_2 - x)\cdots(d_n - x)$ and the coefficient of x^{n-1} in this polynomial must be equal to the coefficient of x^{n-1} in det(A - xI).

By the lemma, the coefficient of x^{n-1} in $(d_1 - x)(d_2 - x)\cdots(d_n - x)$ is $(-1)^{n-1}(d_1 + d_2 + \cdots + d_n) = (-1)^{n-1} \operatorname{tr}(A)$, and so $a_{n-1} = (-1)^{n-1} \operatorname{tr}(A)$.

Here's one way we might use the preceding theorem.

Corollary. Suppose A is a 2×2 matrix. Let $p = \det A$ and $q = \operatorname{tr} A$.

Then A has distinct eigenvalues if and only if $q^2 \neq 4p$.

Proof. Suppose $a, b \in \mathbb{C}$ are the eigenvalues of A (repeated with multiplicity).

Then ab = p and a + b = q so $a(q - a) = qa - a^2 = p$ and therefore $a^2 - qa + p = 0$.

The quadratic formula implies that

$$a = \frac{q \pm \sqrt{q^2 - 4p}}{2}$$
 and $b = \frac{q \mp \sqrt{q^2 - 4p}}{2}$

so we have $a \neq b$ if and only if $q^2 - 4p \neq 0$.

Some other useful properties:

Proposition. If A is a square matrix then A and A^T have the same eigenvalues.

Proof. In fact, A and A^T has the same characteristic polynomial since

$$\det(A - xI) = \det((A - xI)^{T}) = \det(A^{T} - xI^{T}) = \det(A^{T} - xI).$$

Proposition. Let A be a square matrix. Then A is invertible if and only if 0 is not one of its eigenvalues. Assume A is invertible. Then A and A^{-1} have the same eigenvectors, but v is an eigenvector of A with eigenvalue λ if and only if v is an eigenvector of A^{-1} with eigenvalue $1/\lambda$.

Proof. 0 is an eigenvalue of A if and only if det A = 0 which occurs precisely when A is not invertible.

If A is invertible and
$$Av = \lambda v$$
 then $v = A^{-1}Av = A^{-1}\lambda v = \lambda A^{-1}v$ so $A^{-1}v = \lambda^{-1}v$.

Corollary. If A is invertible and diagonalisable then A^{-1} is diagonalisable.

Proof. If A is invertible and diagonalisable, then \mathbb{R}^n has a basis consisting of eigenvectors of A, but this basis is then also made up of eigenvectors of A^{-1} , so A^{-1} is diagonalisable.

Corollary. If A is diagonalisable then A^T is diagonalisable.

Proof. If $A = PDP^{-1}$ then $A^T = (PDP^{-1})^T = (P^{-1})^T D^T P^T = QEQ^{-1}$ for the invertible matrix $Q = (P^{-1})^T = (P^T)^{-1}$ and the diagonal matrix $E = D^T$.

3 Inner products and orthogonality

We return (for the most part) to the setting of vectors in \mathbb{R}^n and matrices with real entries.

Definition. The *inner product* (also called the *dot product*) of two vectors

$$u = \begin{bmatrix} u_1 \\ u_2 \\ \vdots \\ u_n \end{bmatrix} \quad \text{and} \quad \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix}$$

in \mathbb{R}^n is the scalar

 $u \bullet v = u_1 v_1 + u_2 v_2 + \dots + u_n v_n.$

Note that $u \bullet v = u^T v = v^T u = v \bullet u$. For example, $\begin{bmatrix} 2\\ -5\\ -1 \end{bmatrix} \bullet \begin{bmatrix} 3\\ 2\\ -3 \end{bmatrix} = 6 - 10 + 3 = -1$.

In the textbook, the inner product is printed more like " $u \cdot v$." This means the same thing as what I'm writing here as " $u \bullet v$."

Some easy properties of the inner product.

Let $u, v, w \in \mathbb{R}^n$ and $c \in \mathbb{R}$.

- (a) $u \bullet v = v \bullet u$.
- (b) $(u+v) \bullet w = u \bullet w + v \bullet w$.
- (c) $(cu) \bullet v = c(u \bullet v).$

(d)
$$v \bullet v = v_1^2 + v_2^2 + \dots + v_n^2 \ge 0.$$

(e) if $v \bullet v = 0$ ten $v_1 = v_2 = \cdots = v_n = 0 \in \mathbb{R}$ so $v = 0 \in \mathbb{R}^n$.

Definition. The *length* of a vector $v \in \mathbb{R}^n$ is the nonnegative real number

$$||v|| = \sqrt{v \bullet v} = \sqrt{v_1^2 + v_2^2 + \dots + v_n^2}.$$

Although $u \bullet v$ can be any real number, we always have $||v|| \ge 0$.

For any $v \in \mathbb{R}^n$ it holds that $||v||^2 = v \bullet v$ and ||cv|| = |c|||v|| for $c \in \mathbb{R}$.

Lemma. If $v \in \mathbb{R}^n$ then ||v|| = 0 if and only if v = 0.

Proof. The only way we can have
$$||v|| = 0$$
 is if $v_1 = v_2 = \cdots = v_n = 0$.

A vector $v \in \mathbb{R}^n$ is a *unit vector* if ||v|| = 1.

Proposition. If $v \in \mathbb{R}^n$ is a nonzero vector then $u = \frac{1}{\|v\|} v \in \mathbb{R}^n$ is a unit vector.

Proof. We have
$$\left\|\frac{1}{\|v\|}v\right\| = \frac{1}{\|v\|}\|v\| = 1.$$

We refer to $u = \frac{1}{\|v\|}v$ as the unit vector in the same direction as the nonzero vector $v \in \mathbb{R}^n$.

Example. If

$$v = \begin{bmatrix} 1\\ -2\\ 2\\ 0 \end{bmatrix}$$

then $||v|| = \sqrt{1+4+4+0} = \sqrt{9} = 3$ so

$$u = \begin{bmatrix} 1/3 \\ -2/3 \\ 2/3 \\ 0 \end{bmatrix}$$

is the unit vector in the same direction as v.

The distance between two vectors $u, v \in \mathbb{R}^n$ is the length of the their difference ||u - v||.

Definition. Two vectors $u, v \in \mathbb{R}^n$ are orthogonal if $u \bullet v = 0$.

To motivate this definition we consider what it means in 2 dimensions.

Suppose $u = \begin{bmatrix} a \\ b \end{bmatrix}$ and $v = \begin{bmatrix} x \\ y \end{bmatrix}$ are orthogonal vectors in \mathbb{R}^2 , so that ax + by = 0. Assume both u and v are nonzero (since a zero vector is orthogonal to any vector and so is not very interesting to consider). If a = 0 then we must have $b \neq 0 = by$, so y = 0 and $u = \begin{bmatrix} 0 \\ b \end{bmatrix}$ and $v = \begin{bmatrix} x \\ 0 \end{bmatrix} = -\frac{x}{b} \begin{bmatrix} -b \\ 0 \end{bmatrix}$. If $a \neq 0$ then $x = \frac{-b}{a}y$ so $v = \begin{bmatrix} -\frac{b}{a}y \\ y \end{bmatrix} = \frac{y}{a} \begin{bmatrix} -b \\ a \end{bmatrix}$.

We conclude the following from these cases:

Proposition. If $u, v \in \mathbb{R}^2$ are orthogonal and $u = \begin{bmatrix} a \\ b \end{bmatrix}$ then v is a scalar multiple $\begin{bmatrix} -b \\ a \end{bmatrix}$, which is the vector obtained by rotating u counterclockwise by 90 degrees. Thus orthogonal vectors in \mathbb{R}^2 are perpendicular/orthogonal in the usual sense of lines in planar geometry.

Suppose $V \subset \mathbb{R}^n$ is a subspace. The *orthogonal complement* of V is the set

$$V^{\perp} = \{ w \in \mathbb{R}^n : v \bullet w = 0 \text{ for all } v \in V \}.$$

Pronounce " V^{\perp} " as "vee perp."

Proposition. If $V \subset \mathbb{R}^n$ is a subspace then its orthogonal complement $V^{\perp} \subset \mathbb{R}^n$ is also a subspace.

Proof. Since $v \bullet 0 = 0$ for all $v \in \mathbb{R}^n$ it holds that $0 \in V^{\perp}$.

If $x, y \in V^{\perp}$ and $c \in \mathbb{R}$ then $v \bullet cx = c(v \bullet x) = 0$ and $v \bullet (x + y) = v \bullet x + v \bullet y = 0 + 0 = 0$ for all $v \in V$ so cx and x + y both belong to V^{\perp} . Hence V^{\perp} is a subspace.

The operation $(\cdot)^{\perp}$ relates the column space, null space, and transpose of a matrix in the following way:

Theorem. Suppose A is an $m \times n$ matrix. Then $(\operatorname{Col} A)^{\perp} = \operatorname{Nul}(A^T)$.

Proof. Write $A = \begin{bmatrix} a_1 & a_2 & \dots & a_n \end{bmatrix}$ where $a_i \in \mathbb{R}^m$. Let $v \in \mathbb{R}^n$. Then $v \in (\text{Col } A)^{\perp}$ if and only if $v \bullet a_i = a_i^T v = 0$ for all i. This holds if and and only if

$$A^{T}v = \begin{bmatrix} a_{1}^{T} \\ a_{2}^{T} \\ \vdots \\ a_{n}^{T} \end{bmatrix} v = 0 \in \mathbb{R}^{m},$$

i.e., if and only if $v \in \operatorname{Nul}(A^T)$.

Here is our last result for today:

Lemma. Let $V \subset \mathbb{R}^n$ be a subspace. Suppose v_1, v_2, \ldots, v_k is a basis for V and w_1, w_2, \ldots, w_l is a basis for V^{\perp} . Then the concatenated list of vectors $v_1, v_2, \ldots, v_k, w_1, w_2, \ldots, w_l$ is linearly independent. Later, we will show that actually k + l = n so these linearly independent vectors are a basis for \mathbb{R}^n .

Proof. The only way that the vectors $v_1, v_2, \ldots, v_k, w_1, w_2, \ldots, w_l$ can be linearly dependent is if we could write

$$a_1v_1 + \dots + a_kv_k = b_1w_1 + \dots + b_lw_l$$

for some coefficients $a_1, a_2, \ldots, a_k, b_1, b_2, \ldots, b_l \in \mathbb{R}$ which are not all zero. But then there would exist a nonzero vector in both V and V^{\perp} , which is impossible since any $u \in V \cap V^{\perp}$ has $u \bullet u = 0$ so u = 0. \Box