This document is a **transcript** of the lecture, with extra summary and vocabulary sections for your convenience. Due to time constraints, the notes may sometimes only contain limited illustrations, proofs, and examples; for a more thorough discussion of the course content, **consult the textbook**.

Summary

Quick summary of today's notes. Lecture starts on next page.

- The *inner product* or *dot product* of two vectors $u, v \in \mathbb{R}^n$ is the scalar $u \bullet v = u^\top v \in \mathbb{R}$.
- We always have $v \bullet v \geq 0$. The *length* of $v \in \mathbb{R}^n$ is $\|v\| = \sqrt{v \bullet v}$.

  If $c \in \mathbb{R}$ and $v \in \mathbb{R}^n$ then $\|cv\| = |c|\|v\|$.

  The *distance* between $u \in \mathbb{R}^n$ and $v \in \mathbb{R}^n$ is defined to be the length $\|u - v\|$.
- A *unit vector* is a vector $u \in \mathbb{R}^n$ with $\|u\| = 1$.

  If $v \in \mathbb{R}^n$ is any nonzero vector, then the *unit vector in the direction of v* is $u = \frac{1}{\|v\|} v \in \mathbb{R}^n$.
- Two vectors $u, v \in \mathbb{R}^n$ are *orthogonal* if $u \bullet v = 0$.

  If $V \subseteq \mathbb{R}^n$ is a subspace then its *orthogonal complement* is the subspace

  $$V^\perp = \{w \in \mathbb{R}^n : v \bullet w = 0 \text{ for all } v \in V\}.$$

  We always have $V \cap V^\perp = \{0\} \subseteq \mathbb{R}^n$. Next time, we'll see that $\dim V + \dim V^\perp = n$.

  If A is an $m \times n$ matrix then $(\operatorname{Col} A)^\perp = \operatorname{Nul}(A^\top)$.
- An *orthogonal basis* is a basis in which any two vectors are orthogonal.

  Suppose $v_1, v_2, \dots, v_p \in \mathbb{R}^n$ are nonzero vectors with $v_i \bullet v_j = 0$ for all $i \neq j$.

  Then these vectors are linearly independent, and therefore an orthogonal basis for their span.
- Let $u \in \mathbb{R}^n$ be a nonzero vector. Let $L = \mathbb{R}\text{-span}\{u\}$. Suppose $y \in \mathbb{R}^n$ is any vector.

  The *orthogonal projection* of y onto L is the vector $\operatorname{proj}_L(y) = \frac{y \bullet u}{u \bullet u} u \in L$.

  The *component of y orthogonal to L* is the vector $z = y - \operatorname{proj}_L(y) = y - \frac{y \bullet u}{u \bullet u} u \in L^\perp$.

  We always have $\operatorname{proj}_L(y) + z = y$ and $\operatorname{proj}_L(y) \bullet z = 0$.

  These formulas do not depend of the choice of u, only on the subspace L that u spans.

1 Last time: properties of eigenvalues

The *trace* of a square matrix A is the sum of its diagonal entries.

We denote this by the symbol $\mathrm{tr}(A)$. For 2×2 matrices we have $\mathrm{tr}\left(\begin{bmatrix} a & b \\ c & d \end{bmatrix}\right) = a+d$.

Suppose A and B are $n\times n$ matrices. Although in general $\mathrm{tr}(AB) \neq \mathrm{tr}(A)\mathrm{tr}(B)$, we have both

$$\mathrm{tr}(AB) = \mathrm{tr}(BA) \qquad \text{and} \qquad \det(AB) = \det(A)\det(B) = \det(B)\det(A) = \det(BA).$$

Theorem. Let A be an $n\times n$ matrix and write I for the $n\times n$ identity matrix. The fundamental theorem of algebra tells us that there are complex numbers $\lambda_1, \lambda_2, \dots, \lambda_n \in \mathbb{C}$ such that

$$\det(A - xI) = (\lambda_1 - x)(\lambda_2 - x)\cdots(\lambda_n - x).$$

For these numbers it holds that $\det(A) = \lambda_1\lambda_2\cdots\lambda_n$ and $\mathrm{tr}(A) = \lambda_1 + \lambda_2 + \cdots + \lambda_n$.

In words: the product of the eigenvalues of A, repeated with multiplicity, is the determinant of A, while the sum of the eigenvalues of A, repeated with multiplicity, is the trace of A.

The theorem is easy to prove when A is a triangular matrix: for example if $A = \begin{bmatrix} \lambda_1 & a & b \\ 0 & \lambda_2 & c \\ 0 & 0 & \lambda_3 \end{bmatrix}$ then

$$\det(A - xI) = (\lambda_1 - x)(\lambda_2 - x)(\lambda_3 - x) \quad \text{and} \quad \mathrm{tr} A = \lambda_1 + \lambda_2 + \lambda_3 \quad \text{and} \quad \det A = \lambda_1\lambda_2\lambda_3.$$

A few other properties of eigenvalues and eigenvectors worth noting:

Proposition. If A is a square matrix then A and $A^\top$ have the same eigenvalues.

Proof. This follows since $\det(A - xI) = \det((A - xI)^\top) = \det(A^\top - xI^\top) = \det(A^\top - xI)$. □

Proposition. Let A be a square matrix. Then A is invertible if and only if 0 is not one of its eigenvalues.

Proof. 0 is an eigenvalue of A if and only if $\det A = 0$ which occurs precisely when A is not invertible. □

Proposition. Assume A is invertible. Then A and A^{-1} have the same eigenvectors, but v is an eigenvector of A with eigenvalue λ if and only if v is an eigenvector of A^{-1} with eigenvalue λ^{-1}.

Proof. If A is invertible and $Av = \lambda v$ then $v = A^{-1}Av = A^{-1}\lambda v = \lambda A^{-1}v$ so $A^{-1}v = \lambda^{-1}v$. □

Corollary. If A is invertible and diagonalizable then A^{-1} is diagonalizable.

Proof. If A is invertible and diagonalizable, then $\mathbb{R}^n$ has a basis consisting of eigenvectors of A, but this basis is then also made up of eigenvectors of A^{-1}, so A^{-1} is diagonalizable. □

Corollary. If A is diagonalizable then $A^\top$ is diagonalizable.

Proof. Suppose $A = PDP^{-1}$ where D is diagonal. Let $Q = (P^{-1})^\top = (P^\top)^{-1}$.

Then $D^\top = D$ so $A^\top = (PDP^{-1})^\top = (P^{-1})^\top D^\top P^\top = QDQ^{-1}$. □

2 Inner products and orthogonality

In this lecture, we will only work with vectors in $\mathbb{R}^n$ and with matrices that have all real entries.

Definition. The *inner product* or *dot product* of two vectors

$$u = \begin{bmatrix} u_1 \\ u_2 \\ \vdots \\ u_n \end{bmatrix} \quad \text{and} \quad v = \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix}$$

in $\mathbb{R}^n$ is the scalar $u \bullet v = u_1 v_1 + u_2 v_2 + \cdots + u_n v_n = u^\top v = v^\top u = v \bullet u$.

For example, $\begin{bmatrix} a \\ b \end{bmatrix} \bullet \begin{bmatrix} -b \\ a \end{bmatrix} = -ab + ab = 0$ for any $a, b \in \mathbb{R}$.

Definition. The *length* of a vector $v \in \mathbb{R}^n$ is $\|v\| = \sqrt{v \bullet v} = \sqrt{v_1^2 + v_2^2 + \cdots + v_n^2}$.

Essential properties of length and inner product.

Let $u, v, w \in \mathbb{R}^n$ and $c \in \mathbb{R}$.

(a) $u \bullet v = v \bullet u$ and $(u + v) \bullet w = u \bullet w + v \bullet w$ and $(cv) \bullet w = c(v \bullet w)$, while $\|cv\| = |c|\|v\|$.

(b) $v \bullet v = v_1^2 + v_2^2 + \cdots + v_n^2 \geq 0$ and $\|v\| \geq 0$.

(c) $v \bullet v = 0$ if and only if $\|v\| = 0$ if and only if $v = 0 \in \mathbb{R}^n$.

(d) There is a general trigonometric identity relating $u \bullet v$ to the angle θ between u and v:

$$u \bullet v = \|u\|\|v\| \cos \theta.$$

This holds even when $u = 0$ or $v = 0$ (as both sides are zero), although then θ is not defined.

We won't need to use this identity directly very often.

However, it is useful for gaining intuition about the sign of $u \bullet v$: this value is negative if and only if $\cos \theta \in [-1, 0)$, which happens precisely when u and v form an obtuse angle θ.

The *distance* between two vectors $u, v \in \mathbb{R}^n$ is the length of the difference $\|u - v\|$.

A *unit vector* is a vector $u \in \mathbb{R}^n$ with $\|u\| = 1$.

If $v \in \mathbb{R}^n$ is any nonzero vector, then the *unit vector in the direction of v* is $u = \frac{1}{\|v\|} v \in \mathbb{R}^n$.

Note that for this u we have $\|u\| = \|\frac{1}{\|v\|} v\| = |\frac{1}{\|v\|}|\|v\| = \frac{1}{\|v\|}\|v\| = 1$.

Example. The unit vector in the direction of $v = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}$ is $u = \frac{1}{\sqrt{1^2+1^2+1^2+1^2}} v = \begin{bmatrix} 1/2 \\ 1/2 \\ 1/2 \\ 1/2 \end{bmatrix}$.

Definition. Two vectors $u, v \in \mathbb{R}^n$ are *orthogonal* if $u \bullet v = 0$.

When u and v are orthogonal we also say that "u is orthogonal to v."'

Proposition. Suppose $u, v \in \mathbb{R}^2$ are nonzero vectors that are orthogonal to each other, so that $u \bullet v = 0$. Then u and v, drawn as arrows in the xy-plane, belong to perpendicular lines through the origin. In other words, these vectors are perpendicular in the usual sense of planar geometry.

Concretely, if $u, v \in \mathbb{R}^2$ are orthogonal and $0 \neq u = \begin{bmatrix} a \\ b \end{bmatrix}$, then v is a scalar multiple $\begin{bmatrix} -b \\ a \end{bmatrix}$, which is the vector obtained by rotating u counterclockwise by 90 degrees.

Proof. This follows directly from the identity $u \bullet v = \|u\|\|v\| \cos\theta$, which implies that $u \bullet v = 0$ if and only if the angle θ between u and v is $\pm\frac{\pi}{2}$. Below is a more self-contained proof.

Write $u = \begin{bmatrix} a \\ b \end{bmatrix}$ and $v = \begin{bmatrix} x \\ y \end{bmatrix}$. Then $u \bullet v = ax + by = 0$.

If $a = 0$ then $b \neq 0$ since $u \neq 0$, so $y = -\frac{a}{b}x = 0$ and $v = \begin{bmatrix} x \\ 0 \end{bmatrix} = -\frac{x}{b}\begin{bmatrix} -b \\ 0 \end{bmatrix}$.

If $a \neq 0$ then $x = \frac{-b}{a}y$ so $v = \begin{bmatrix} -\frac{b}{a}y \\ y \end{bmatrix} = \frac{y}{a}\begin{bmatrix} -b \\ a \end{bmatrix}$. Thus v is a scalar multiple of $\begin{bmatrix} -b \\ a \end{bmatrix}$.

To see that $\begin{bmatrix} a \\ b \end{bmatrix}$ and $\begin{bmatrix} -b \\ a \end{bmatrix}$ are perpendicular, note that $\begin{bmatrix} -b \\ a \end{bmatrix} = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}\begin{bmatrix} a \\ b \end{bmatrix}$.

The 2-by-2 matrix $\begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$ acts by rotating a vector 90 degrees counterclockwise. □

3 Orthogonal complements

Let $V \subseteq \mathbb{R}^n$ be a subspace. The *orthogonal complement* of V is $V^\perp = \{w \in \mathbb{R}^n : v \bullet w = 0 \text{ for all } v \in V\}$.

We pronounce "$V^\perp$" as "vee perp."

Proposition. If $V \subseteq \mathbb{R}^n$ is a subspace then its orthogonal complement $V^\perp \subseteq \mathbb{R}^n$ is also a subspace.

Proof. Since $v \bullet 0 = 0$ for all $v \in \mathbb{R}^n$ it holds that $0 \in V^\perp$. This confirms that $V^\perp$ is nonempty.

If $x, y \in V^\perp$ and $c \in \mathbb{R}$ then $v \bullet cx = c(v \bullet x) = 0$ and $v \bullet (x + y) = v \bullet x + v \bullet y = 0 + 0 = 0$ for all $v \in V$ so cx and $x + y$ both belong to $V^\perp$. Hence $V^\perp$ is a subspace. □

The operation $(\cdot)^\perp$ relates the column space, null space, and transpose of a matrix in the following way:

Theorem. Suppose A is an $m \times n$ matrix. Then $(\mathrm{Col}\, A)^\perp = \mathrm{Nul}(A^\top) \subseteq \mathbb{R}^m$.

Proof. Write $A = \begin{bmatrix} a_1 & a_2 & \dots & a_n \end{bmatrix}$ where $a_i \in \mathbb{R}^m$. Let $v \in \mathbb{R}^m$.

If $v \in (\mathrm{Col}\, A)^\perp$ then we must have $v \bullet a_i = a_i^\top v = 0$ for all i.

Conversely, if $v \bullet a_i = a_i^\top v = 0$ for all i then

$$(c_1 a_1 + c_2 a_2 + \dots + c_n a_n) \bullet v = c_1 \underbrace{(a_1 \bullet v)}_{=0} + c_2 \underbrace{(a_2 \bullet v)}_{=0} + \dots + c_n \underbrace{(a_n \bullet v)}_{=0} = 0$$

for any scalars $c_1, c_2, \dots, c_n \in \mathbb{R}$ so $v \in (\mathrm{Col}\, A)^\perp$.

Thus $v \in (\mathrm{Col}\, A)^\perp$ if and only if $v \bullet a_i = a_i^\top v = 0$ for all i. This holds if and and only if

$$A^\top v = \begin{bmatrix} a_1^\top \\ a_2^\top \\ \vdots \\ a_n^\top \end{bmatrix} v = \begin{bmatrix} a_1 \bullet v \\ a_2 \bullet v \\ \vdots \\ a_n \bullet v \end{bmatrix} = 0 \in \mathbb{R}^m, \quad \text{which means that } v \in \mathrm{Nul}(A^\top).$$

□

Lemma. Let $V \subseteq \mathbb{R}^n$ be a subspace. If $w \in V \cap V^\perp$ then $w = 0$.

Proof. If $w \in V$ and $w \in V^\perp$ then $w \bullet w = 0$ so $w = 0$. □

Proposition. Let $V \subseteq \mathbb{R}^n$ be a subspace. If $S \subseteq V$ and $T \subseteq V^\perp$ are two sets of linearly independent vectors, then $S \cup T$ is also linearly independent.

Proof. Suppose there was a nontrivial linear dependence among the elements of $S \cup T$ equal to zero. Rewrite this linear dependence so that the terms from S are on the left side of the equals sign and the terms from T are on the other side. Then we would have an equation of the form

$$\underbrace{a_1 v_1 + \cdots + a_k v_k}_{\in V} = \underbrace{b_1 w_1 + \cdots + b_l w_l}_{\in V^\perp}$$

where $v_1, \dots, v_k \in S$ and $w_1, \dots, w_l \in T$, for some coefficients $a_1, a_2, \dots, a_k, b_1, b_2, \dots, b_l \in \mathbb{R}$ which are not all zero. But such an equation would imply that a nonzero element of V is equal to a nonzero element of $V^\perp$, which is impossible by the lemma. □

Corollary. If $V \subseteq \mathbb{R}^n$ is a subspace then $\dim V^\perp \leq n - \dim V$.

Proof. If S is a basis for V and T is a basis for $V^\perp$ then $\dim V + \dim V^\perp = |S| + |T| = |S \cup T|$. Since $S \cup T$ is a set of linearly independent vectors in $\mathbb{R}^n$, its size must be at most n. □

4 Orthogonal bases and orthogonal projections

The following proposition is called the *Generalized Pythagorean theorem*.

Proposition. Two vectors $u, v \in \mathbb{R}^n$ are orthogonal if and only if $\|u + v\|^2 = \|u\|^2 + \|v\|^2$.

Proof. The proof is just a little algebra:

$$\|u+v\|^2 = (u+v) \bullet (u+v) = u \bullet (u+v) + v \bullet (u+v) = u \bullet u + u \bullet v + v \bullet u + v \bullet v = \|u\|^2 + \|v\|^2 + 2(u \bullet v).$$

Then $\|u + v\|^2 = \|u\|^2 + \|v\|^2$ if and only if $u \bullet v = 0$.

The equivalence of this proposition to the classical Pythagorean theorem boils down to our observation earlier that orthogonal vectors in $\mathbb{R}^2$ form the sides of a right triangle. □

A collection of vectors $u_1, u_2, \dots, u_p \in \mathbb{R}^n$ is *orthogonal* if $u_i \bullet u_j = 0$ whenever $1 \leq i < j \leq p$.

In particular, an *orthogonal basis* of $\mathbb{R}^n$ is a basis in which any two vectors are orthogonal.

For example, the standard basis $e_1, e_2, \dots, e_n$ is an orthogonal basis for $\mathbb{R}^n$.

Theorem. Suppose the vectors $u_1, u_2, \dots, u_p \in \mathbb{R}^n$ are orthogonal and all nonzero.

Then $u_1, u_2, \dots, u_p$ are linearly independent.

Proof. Suppose $c_1u_1 + c_2u_2 + \cdots + c_pu_p = 0$ for some coefficients $c_1, c_2, \dots, c_p \in \mathbb{R}$.

For each $i = 1, 2, \dots, p$, we then have

$$0 = (c_1u_1 + c_2u_2 + \cdots + c_pu_p) \bullet u_i = c_1(u_1 \bullet u_i) + c_2(u_2 \bullet u_i) + \cdots + c_p(u_p \bullet u_i) = c_i\|u_i\|^2$$

since $u_j \bullet u_i = 0$ if $i \neq j$. But since u_i is nonzero, $\|u_i\|^2 \neq 0$, so it must hold that $c_i = 0$. As this argument applies to each index i, we deduce that $c_1 = c_2 = \cdots = c_p = 0$.

In other words, the only way we can have $c_1u_1 + c_2u_2 + \cdots + c_pu_p = 0$ is if all of the coefficients are zero, which is the definition of linear independence. □

Corollary. Any set of nonzero, orthogonal vectors is an orthogonal basis for the subspace they span.

Any set of n nonzero, orthogonal vectors in $\mathbb{R}^n$ is an orthogonal basis for $\mathbb{R}^n$.

Proposition. Suppose $u_1, u_2, \dots, u_p$ is an orthogonal basis for a subspace $V \subseteq \mathbb{R}^n$.

Let $y \in V$. Then we can write $y = c_1u_1 + c_2u_2 + \cdots + c_pu_p$ where

$$c_i = \frac{y \bullet u_i}{u_i \bullet u_i} = \frac{y \bullet u_i}{\|u_i\|^2}.$$

Proof. A basis must span V, so $y = c_1u_1 + c_2u_2 + \cdots + c_pu_p$ for some coefficients $c_1, c_2, \dots, c_p \in \mathbb{R}$.

Since $y \bullet u_i = c_i(u_i \bullet u_i)$ for each $i = 1, 2, \dots, p$, the result follows. □

Example. Suppose $u_1 = \begin{bmatrix} 3 \\ 1 \\ 1 \end{bmatrix}$ and $u_2 = \begin{bmatrix} -1 \\ 2 \\ 1 \end{bmatrix}$ and $u_3 = \begin{bmatrix} -1/2 \\ -2 \\ 7/2 \end{bmatrix}$.

You can check that these three vectors are orthogonal.

For example, $u_1 \bullet u_3 = -3/2 - 2 + 7/2 = 0$.

The vectors are therefore linearly independent, so are an orthogonal basis for $\mathbb{R}^3$.

For $y = \begin{bmatrix} 6 \\ 1 \\ 8 \end{bmatrix}$ we have $y \bullet u_1 = 11$ and $y \bullet u_2 = -12$ and $y \bullet u_3 = -33$.

We also have $u_1 \bullet u_1 = 11$ and $u_2 \bullet u_2 = 6$ and $u_3 \bullet u_3 = 33/2$. Therefore $y = u_1 - 2u_2 - 2u_3$.

Let $u \in \mathbb{R}^n$ be a nonzero vector. Suppose $y \in \mathbb{R}^n$ is any vector.

Definition. The *orthogonal projection* of y onto u is the vector $\boxed{\widehat{y} = \frac{y \bullet u}{u \bullet u}u.}$

This vector is scalar multiple of u, and can be zero.

The *component of y orthogonal to u* is the vector $\boxed{z = y - \widehat{y} = y - \frac{y \bullet u}{u \bullet u}u.}$

It always holds that $y = \widehat{y} + z$. Moreover, as its name suggests, we have $z \bullet u = 0$ since

$$z \bullet u = y \bullet u - \frac{y \bullet u}{u \bullet u}u \bullet u = y \bullet u - y \bullet u = 0.$$

Observation. The vectors $\widehat{y}$ and z do not change if u is replaced by a nonzero scalar multiple: if we change u to cu for some $0 \neq c \in \mathbb{R}$ then all the factors of c cancel:

$$\frac{y \bullet cu}{cu \bullet cu} cu = \frac{c(y \bullet u)}{c^2(u \bullet u)} cu = \frac{y \bullet u}{u \bullet u} u = \widehat{y}.$$

Let $L = \mathbb{R}\text{-span}\{u\}$. Then $\widehat{y}$ and z may also be called the *orthogonal projection* of y onto L the *component* of y orthogonal to L. We will write $\boxed{\text{proj}_L(y) = \widehat{y} \in L.}$

In $\mathbb{R}^2$, the distance from a point (x, y) to a line $L = \mathbb{R}\text{-span}\{u\}$ is the length $\left\| \begin{bmatrix} x \\ y \end{bmatrix} - \text{proj}_L\left(\begin{bmatrix} x \\ y \end{bmatrix} \right) \right\|$.

Example. To find the distance from the point $(x, y) = (7, 6)$ to the line L defined by $y = \frac{1}{2}x$, note that L contains the vector $u = \begin{bmatrix} 4 \\ 2 \end{bmatrix}$. Let $w = \begin{bmatrix} 7 \\ 6 \end{bmatrix}$. Then $\text{proj}_L\left(\begin{bmatrix} 7 \\ 6 \end{bmatrix} \right) = \frac{w \bullet u}{u \bullet u} u = \frac{28+12}{16+4} u = \frac{40}{20} u = \begin{bmatrix} 8 \\ 4 \end{bmatrix}$ so the distance is $\left\| \begin{bmatrix} 7 \\ 6 \end{bmatrix} - \begin{bmatrix} 8 \\ 4 \end{bmatrix} \right\| = \left\| \begin{bmatrix} -1 \\ 2 \end{bmatrix} \right\| = \sqrt{1+4} = \sqrt{5}$.

5 Vocabulary

Keywords from today's lecture:

1. **Inner product** of vectors $u, v \in \mathbb{R}^n$.

   The scalar $u \bullet v = u^\top v \in \mathbb{R}$.

   Example: $\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} \bullet \begin{bmatrix} -1 \\ -10 \\ -100 \end{bmatrix} = -1 - 20 - 300 = -321.$

2. **Length** of a vector $v \in \mathbb{R}^n$ and **distance** between $u, v \in \mathbb{R}^n$.

   The *length* of $v \in \mathbb{R}^n$ is $\|v\| = \sqrt{v \bullet v} = \sqrt{v_1^2 + v_2^2 + \dots + v_n^n}$ where $v = \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix}$.

   The *distance* from $u \in \mathbb{R}^n$ to $v \in \mathbb{R}^n$ is $\|u - v\|$.

3. **Unit vector**.

   A *unit vector* is a vector in $\mathbb{R}^n$ with length 1.

   The unit vector in the same direction as a nonzero vector $v \in \mathbb{R}^n$ is $u = \frac{1}{\|v\|} v$.

4. **Orthogonal vectors**.

   Two vectors $u, v \in \mathbb{R}^n$ are *orthogonal* if $u \bullet v = 0$.

   A collection of vectors in $\mathbb{R}^n$ is orthogonal if any two of the vectors are orthogonal.

   A basis of a subspace is *orthogonal* if any two vectors in the basis are orthogonal.

   Example: In $\mathbb{R}^2$, the vectors $\begin{bmatrix} a \\ b \end{bmatrix}$ and $\begin{bmatrix} -b \\ a \end{bmatrix}$ are always orthogonal.

5. **Orthogonal complement** of a subspace $V \subseteq \mathbb{R}^n$.

   The subspace $V^\perp = \{w \in \mathbb{R}^n : v \bullet w = 0 \text{ for all } v \in V\}$.

   Example: If $V = \mathbb{R}\text{-span}\{e_1, e_2, \dots, e_i\} \subseteq \mathbb{R}^n$ then $V^\perp = \mathbb{R}\text{-span}\{e_{i+1}, e_{i+2}, \dots, e_n\}$.

   If $V = \mathbb{R}^n$ then $V^\perp = \{0\}$. If $V = \{0\} \subseteq \mathbb{R}^n$ then $V^\perp = \mathbb{R}^n$.

6. **Orthogonal projection** of a vector $y \in \mathbb{R}^n$ onto a line $L = \mathbb{R}\text{-span}\{u\}$ where $0 \neq u \in \mathbb{R}^n$.

   The unique vector $\text{proj}_L(y) \in L$ such that $y - \text{proj}_L(y)$ is orthogonal to all vectors in L.

   This vector has the formula $\text{proj}_L(y) = \frac{y \bullet u}{u \bullet u} u$ for any choice of $0 \neq u \in L$.

   The value of $\text{proj}_L(y)$ given by this formula does not change if u is replaced by cu for $0 \neq c \in \mathbb{R}$.

   Example: if $u = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ and $y = \begin{bmatrix} a \\ b \end{bmatrix}$ then $\text{proj}_L(y) = \frac{1}{2} \begin{bmatrix} a+b \\ a+b \end{bmatrix}$.