

This document is an **exact transcript** of the lecture, with extra summary and vocabulary sections. Due to time constraints, the lectures sometimes only contain limited illustrations, proofs, and examples. For a more thorough discussion of the course content, **consult the textbook**.

Summary

Quick summary of today's notes. Lecture starts on next page.

- A **vector space** is a nonempty set with a “zero vector” and two operations that can be thought of a “vector addition” and “scalar multiplication.” The operations must obey several conditions.
- There are notions of **subspaces**, **linear functions**, **linear combinations**, **spans**, **linear independence**, and **bases** for vector spaces. The definitions are essentially the same as for $\mathbb{R}^n$, with one minor caveat when we are considering linear combinations and independence of infinite sets of vectors.
- Every vector space has a basis, and every basis for a given vector space has the same number of elements, which could be infinite. This number of elements is the **dimension** of the vector space.
- If X and Y are sets, then let $\text{Functions}(X, Y)$ be the set of functions $f : X \rightarrow Y$.

The set $\text{Functions}(X, \mathbb{R})$ is naturally a vector space. If X is finite then $\dim \text{Functions}(X, \mathbb{R}) = |X|$.

- If U and V are vector spaces, then let $\text{Lin}(U, V)$ be the set of linear functions $f : U \rightarrow V$.

The set $\text{Lin}(U, V)$ is naturally a vector space. If $\dim U < \infty$ then $\dim \text{Lin}(U, \mathbb{R}) = \dim U$.

Moreover, if W is another vector space and $f \in \text{Lin}(V, W)$ and $g \in \text{Lin}(U, V)$, then $f \circ g \in \text{Lin}(U, W)$.

- Suppose $f : U \rightarrow V$ is a linear function between vector spaces.

Define $\text{range}(f) = \{f(u) : u \in U\} \subseteq V$ and $\text{kernel}(f) = \{u \in U : f(u) = 0\} \subseteq U$.

These sets are subspaces. If $\dim U < \infty$ then $\dim \text{range}(f) + \dim \text{kernel}(f) = \dim U$.

- Let A be an $n \times n$ matrix. Let λ be a number and suppose $0 \neq v \in \mathbb{R}^n$.

If $Av = \lambda v$ then we say that v is an **eigenvector** for A and that λ is an **eigenvalue** for A .

More specifically, v is an **eigenvector with eigenvalue λ** for A .

This happens if and only if $0 \neq v \in \text{Nul}(A - \lambda I_n)$.

For example, $v = \begin{bmatrix} 6 \\ -5 \end{bmatrix}$ is an eigenvector with eigenvalue $\lambda = -4$ for $A = \begin{bmatrix} 1 & 6 \\ 5 & 2 \end{bmatrix}$ since

$$\begin{bmatrix} 1 & 6 \\ 5 & 2 \end{bmatrix} \begin{bmatrix} 6 \\ -5 \end{bmatrix} = \begin{bmatrix} -24 \\ 20 \end{bmatrix} = -4 \begin{bmatrix} 6 \\ -5 \end{bmatrix}.$$

The zero vector is not allowed to be an eigenvector, but 0 can occur as an eigenvalue.

- The eigenvalues λ for A are the numbers such that $\det(A - \lambda I_n) = 0$.
- The eigenvectors with eigenvalue λ for A are the nonzero elements of $\text{Nul}(A - \lambda I_n)$.
- If A is a triangular matrix, then its eigenvalues are its diagonal entries.

For example, the eigenvalues of $\begin{bmatrix} 1 & 6 & 0 \\ 0 & 0 & 3 \\ 0 & 0 & 1 \end{bmatrix}$ are 0 and 1.

1 Last time: vector spaces

A (*real*) *vector space* V is a set containing a *zero vector*, denoted 0 , with *vector addition* and *scalar multiplication* operations that let us produce new vectors $u + v \in V$ and $cv \in V$ from given elements $u, v \in V$ and $c \in \mathbb{R}$. Several conditions must be satisfied so that these operations behave exactly like vector addition and scalar multiplication for $\mathbb{R}^n$. Most importantly, we require that

1. $u + v = v + u$ and $(u + v) + w = u + (v + w)$.
2. $v - v = 0$ where we define $u - v = u + (-1)v$.
3. $v + 0 = v$
4. $cv = v$ if $c = 1$.

There are a few other more conditions to give the full definition (see the notes from last time).

By convention, we refer to elements of vector spaces as *vectors*.

Example. All subspaces of $\mathbb{R}^n$ are vector spaces, with the usual zero vector and vector operations.

The set of $m \times n$ matrices is a vector space, with the usual addition and scalar multiplication operations. The zero vector in this vector space is the $m \times n$ zero matrix.

Most vector spaces that we encounter are either subspaces of $\mathbb{R}^n$ or subspaces of the following construction.

Proposition. Let X be a set and let V be a vector space.

Then the set $\text{Functions}(X, V)$ of all functions $f : X \rightarrow V$ is a vector space once we define

$$\begin{aligned} f + g &= (\text{ the function that maps } x \mapsto f(x) + g(x) \text{ for } x \in X), \\ cf &= (\text{ the function that maps } x \mapsto c \cdot f(x) \text{ for } x \in X), \\ 0 &= (\text{ the function that maps } x \mapsto 0 \in V \text{ for } x \in X), \end{aligned}$$

for $f, g \in \text{Functions}(X, V)$ and $c \in \mathbb{R}$.

A subset $H \subseteq V$ is a *subspace* if $0 \in H$ and if $u + v \in H$ and $cv \in H$ for all $u, v \in H$ and $c \in \mathbb{R}$.

Let V be a vector space. The definitions of *linear combinations*, *span* and *linear independence* for vectors in V are the same as for vectors in $\mathbb{R}^n$. Remember that we can only evaluate the linear combination $c_1v_1 + c_2v_2 + \dots$ if it is a finite sum, or if there are finitely many nonzero scalars $c_i \neq 0$.

Example. The subspace of polynomials in $\text{Functions}(\mathbb{R}, \mathbb{R})$ is the span of the set of functions $1, x, x^2, x^3, \dots$.

The infinite sum $e^x = 1 + x + \frac{1}{2}x^2 + \frac{1}{6}x^3 + \dots + \frac{1}{n!}x^n + \dots$ does not belong to this subspace.

Definition. A *basis* of a vector space V is a subset of linearly independent vectors whose span is V . Saying $b_1, b_2, b_3, \dots$ is a basis for V is the same as saying that for each $v \in V$, there are unique coefficients $x_1, x_2, x_3, \dots \in \mathbb{R}$, **all but finitely many of which are zero**, such that $v = x_1b_1 + x_2b_2 + x_3b_3 + \dots$.

Theorem. Let V be a vector space. Then V has at least one basis, and every basis of V has the same number of elements (but this could be infinite).

Definition. The *dimension* of a vector space V is the number $\dim V$ of elements in any of its bases.

Example. If X is a finite set then $\dim \text{Functions}(X, \mathbb{R}) = |X|$ where $|X|$ is the size of X .

2 Linear functions

Suppose U and V are vector spaces.

Definition. A function $f : U \rightarrow V$ is *linear* if

$$f(u + v) = f(u) + f(v) \quad \text{and} \quad f(cv) = cf(v) \quad \text{for all } c \in \mathbb{R} \text{ and } u, v \in U.$$

Proposition. If U, V, W are vector spaces and $f : V \rightarrow W$ and $g : U \rightarrow V$ are linear functions then $f \circ g : U \rightarrow W$ is also linear, where we define $f \circ g(x) = f(g(x))$ for $x \in U$.

Proof. The proof is the same as when $U = \mathbb{R}^n$, $V = \mathbb{R}^m$, and $W = \mathbb{R}^p$. □

Let $\text{Lin}(U, V)$ be the set of linear functions $f : U \rightarrow V$.

Then $\text{Lin}(U, V)$ is a subspace of $\text{Functions}(U, V)$.

Proposition. If V is a finite-dimensional vector space then $\dim \text{Lin}(V, \mathbb{R}) = \dim V$.

Proof. Suppose $b_1, b_2, \dots, b_n$ is a basis for V .

Then a basis for $\text{Lin}(V, \mathbb{R})$ is given by the linear functions $\phi_1, \phi_2, \dots, \phi_n : V \rightarrow \mathbb{R}$ with the formulas

$$\phi_i(x_1 b_1 + x_2 b_2 + \dots + x_n b_n) = x_i \quad \text{for } x_1, x_2, \dots, x_n \in \mathbb{R}.$$

The unique way to express a linear function $f : V \rightarrow \mathbb{R}$ as a linear combination of these functions is

$$f = f(b_1)\phi_1 + f(b_2)\phi_2 + \dots + f(b_n)\phi_n.$$

□

Remark. Assume $V = \mathbb{R}^n$. Then we can think of $\text{Lin}(\mathbb{R}^n, \mathbb{R})$ as the vector space of $1 \times n$ matrices.

If $b_1 = e_1, b_2 = e_2, \dots, b_n = e_n$ is the standard basis, then $\phi_1 = e_1^\top, \phi_2 = e_2^\top, \dots, \phi_n = e_n^\top$.

Definition. Suppose U and V are vector spaces and $f : U \rightarrow V$ is a linear function.

Define $\text{range}(f) = \{f(x) : x \in U\} \subseteq V$ and $\text{kernel}(f) = \{x \in U : f(x) = 0\} \subseteq U$.

These sets are subspaces which generalize the column space and null space of a matrix.

We have a version of the rank-nullity theorem for arbitrary vector spaces:

Theorem (Rank-Nullity Theorem). If $\dim U < \infty$ then $\dim \text{range}(f) + \dim \text{kernel}(f) = \dim U$.

This specializes to our earlier statement about matrices when $U = \mathbb{R}^n$ and $V = \mathbb{R}^m$.

We can prove the theorem in a self-contained, completely abstract way, but it's a little involved.

Proof. If $b_1, b_2, \dots, b_n$ is a basis for U then the span of $f(b_1), f(b_2), \dots, f(b_n)$ must be equal to $\text{range}(f)$. Therefore $\dim \text{range}(f) \leq \dim U < \infty$. Since $\text{kernel}(f) \subseteq U$, we also have $\dim \text{kernel}(f) < \infty$.

Let $k = \dim \text{range}(f)$ and $l = \dim \text{kernel}(f)$.

Choose $u_1, u_2, \dots, u_k \in U$ such that $f(u_1), f(u_2), \dots, f(u_k)$ is a basis for $\text{range}(f)$.

Choose a basis $v_1, v_2, \dots, v_l$ for $\text{kernel}(f)$. We will check that $u_1, u_2, \dots, u_k, v_1, v_2, \dots, v_l$ is a basis for U .

To show linear independence, suppose $a_1, a_2, \dots, a_k, b_1, b_2, \dots, b_l \in \mathbb{R}$ are such that

$$a_1 u_1 + a_2 u_2 + \dots + a_k u_k + b_1 v_1 + b_2 v_2 + \dots + b_l v_l = 0.$$

Applying f to both sides gives $a_1 f(u_1) + a_2 f(u_2) + \dots + a_k f(u_k) = 0$, so $a_1 = a_2 = \dots = a_k = 0$.

But this implies $b_1 v_1 + b_2 v_2 + \dots + b_l v_l = 0$, so we also have $b_1 = b_2 = \dots = b_l = 0$.

Our vectors $u_1, u_2, \dots, u_k, v_1, v_2, \dots, v_l$ are therefore linearly independent in U .

Now let $x \in U$. By assumption $f(x) = c_1 f(u_1) + c_2 f(u_2) + \dots + c_k f(u_k)$ for some $c_1, c_2, \dots, c_k \in \mathbb{R}$.

The vector $x - c_1 u_1 - c_2 u_2 - \dots - c_k u_k$ is then in the span of $v_1, v_2, \dots, v_l$ since it belongs to $\text{kernel}(f)$.

We conclude that x is a linear combination of $u_1, u_2, \dots, u_k, v_1, v_2, \dots, v_l$, so this is a basis for U . $\square$

3 Eigenvectors and eigenvalues

We return to the concrete setting of $\mathbb{R}^n$ and its subspaces. Let A be a square $n \times n$ matrix.

Definition. An *eigenvector* of A is a **nonzero** vector $v \in \mathbb{R}^n$ such that

$$Av = \lambda v$$

for a number $\lambda \in \mathbb{R}$. (λ is the Greek letter “lambda.”)

The number λ is called the *eigenvalue* of A for the eigenvector v .

We require eigenvectors to be nonzero because if $v = 0$ then $Av = \lambda v = 0$ for all numbers $\lambda \in \mathbb{R}$.

The number 0 is allowed to be an eigenvalue of A , however.

Example. If we are given A and v , it is easy to check whether v is an eigenvector: just compute Av .

For example, if $A = \begin{bmatrix} 1 & 6 \\ 5 & 2 \end{bmatrix}$ and $v = \begin{bmatrix} 6 \\ -5 \end{bmatrix}$ then $Av = \begin{bmatrix} 1 & 6 \\ 5 & 2 \end{bmatrix} \begin{bmatrix} 6 \\ -5 \end{bmatrix} = \begin{bmatrix} -24 \\ 20 \end{bmatrix} = -4v$.

Therefore v is an eigenvector of A with eigenvalue -4 .

Example. What are the eigenvectors of the matrix $A = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$?

If $v \in \mathbb{R}^4$ were an eigenvector with eigenvalue λ then

$$Av = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \\ v_4 \end{bmatrix} = \begin{bmatrix} v_2 \\ v_3 \\ v_4 \\ 0 \end{bmatrix} = \lambda \begin{bmatrix} v_1 \\ v_2 \\ v_3 \\ v_4 \end{bmatrix}.$$

The last equation implies that $0 = \lambda v_4$ and $v_4 = \lambda v_3$ and $v_3 = \lambda v_2$ and $v_2 = \lambda v_1$. In other words,

$$0 = \lambda v_4 = \lambda^2 v_3 = \lambda^3 v_2 = \lambda^4 v_1.$$

If $\lambda \neq 0$ then this would mean that $v_1 = v_2 = v_3 = v_4 = 0$, but remember that v should be nonzero. Therefore the only possible eigenvalue of A is $\lambda = 0$. The eigenvectors of A with eigenvalue 0 are

$$v = \begin{bmatrix} v_1 \\ 0 \\ 0 \\ 0 \end{bmatrix} \quad \text{where } v_1 \neq 0.$$

To say that “ λ is an eigenvalue of A ” means that there exists a nonzero vector $v \in \mathbb{R}^n$ such that $Av = \lambda v$.

Recall that I_n denotes the $n \times n$ identity matrix. We abbreviate by setting $I = I_n$.

Proposition. A number $\lambda \in \mathbb{R}$ is an eigenvalue of A if and only if $A - \lambda I$ is not invertible.

Proof. The equation $Ax = \lambda x$ has a nonzero solution $x \in \mathbb{R}^n$ if and only if $(A - \lambda I)x = 0$ has a nonzero solution, which occurs if and only if $\text{Nul}(A - \lambda I) \neq \{0\}$, or equivalently when $A - \lambda I$ is not invertible. $\square$

Example. If $A = \begin{bmatrix} 1 & 6 \\ 5 & 2 \end{bmatrix}$ then

$$A - 7I = \begin{bmatrix} 1 & 6 \\ 5 & 2 \end{bmatrix} - \begin{bmatrix} 7 & 0 \\ 0 & 7 \end{bmatrix} = \begin{bmatrix} -6 & 6 \\ 5 & -5 \end{bmatrix} \sim \begin{bmatrix} 1 & -1 \\ 1 & -1 \end{bmatrix} \sim \begin{bmatrix} 1 & -1 \\ 0 & 0 \end{bmatrix} = \text{RREF}(A - 7I).$$

Since $\text{RREF}(A - 7I) \neq I$, the matrix $A - 7I$ is not invertible so 7 is an eigenvalue of A .

Corollary. A number $\lambda \in \mathbb{R}$ is an eigenvalue of A if and only if $\det(A - \lambda I) = 0$.

Proof. Remember that $A - \lambda I$ is not invertible if and only if $\det(A - \lambda I) = 0$. $\square$

Another way of defining an eigenvector: the eigenvectors of A with eigenvalue λ are precisely the nonzero elements of the null space $\text{Nul}(A - \lambda I)$. Since we know how to construct a basis for the null space of any matrix, we also know how to find all eigenvectors of a matrix for any given eigenvalue.

Example. In the previous example, $\text{RREF}(A - 7I) = \begin{bmatrix} 1 & -1 \\ 0 & 0 \end{bmatrix}$ so $Ax = 7x$ if and only if $(A - 7I)x = 0$

if and only if $x = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$ where $x_1 - x_2 = 0$. In this linear system, x_2 is a free variable, and we can rewrite x as $x = \begin{bmatrix} x_2 \\ x_2 \end{bmatrix} = x_2 \begin{bmatrix} 1 \\ 1 \end{bmatrix}$. This means $\begin{bmatrix} 1 \\ 1 \end{bmatrix}$ is a basis for $\text{Nul}(A - 7I)$.

Therefore every eigenvector of A with eigenvalue 7 has the form $\begin{bmatrix} a \\ a \end{bmatrix}$ for some $a \in \mathbb{R}$.

One calls the set of all $v \in \mathbb{R}^n$ with $Av = \lambda v$ the *eigenspace* of A for λ . We also call this the *λ -eigenspace* of A . Note that this is just the null space of $A - \lambda I$. A number is an eigenvalue of A if and only if the corresponding eigenspace is nonzero (that is, contains a nonzero vector).

Example. Suppose we were told that $A = \begin{bmatrix} 4 & -1 & 6 \\ 2 & 1 & 6 \\ 2 & -1 & 8 \end{bmatrix}$ has 2 as an eigenvalue.

To find a basis for the 2-eigenspace of A , we row reduce

$$A - 2I = \begin{bmatrix} 2 & -1 & 6 \\ 2 & -1 & 6 \\ 2 & -1 & 6 \end{bmatrix} \sim \begin{bmatrix} 2 & -1 & 6 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & -1/2 & 3 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} = \text{RREF}(A - 2I).$$

Thus $Ax = 2x$ if and only if $x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$ where $x_1 - \frac{1}{2}x_2 + 3x_3 = 0$, that is, if and only if

$$x = \begin{bmatrix} \frac{1}{2}x_2 - 3x_3 \\ x_2 \\ x_3 \end{bmatrix} = x_2 \begin{bmatrix} 1/2 \\ 1 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} -3 \\ 0 \\ 1 \end{bmatrix}.$$

The vectors $\begin{bmatrix} 1/2 \\ 1 \\ 0 \end{bmatrix}$ and $\begin{bmatrix} -3 \\ 0 \\ 1 \end{bmatrix}$ are then a basis for the 2-eigenspace of A .

Recall that a matrix is *triangular* if its nonzero entries all appear on or above the main diagonal, or all appear on or below the main diagonal.

Theorem. The eigenvalues of a triangular square matrix A are its diagonal entries.

Proof. If A has diagonal entries $d_1, d_2, \dots, d_n$ then $A - \lambda I$ is triangular with diagonal entries $d_1 - \lambda, d_2 - \lambda, \dots, d_n - \lambda$, so $\det(A - \lambda I) = (d_1 - \lambda)(d_2 - \lambda) \cdots (d_n - \lambda)$ which is zero if and only if $\lambda \in \{d_1, d_2, \dots, d_n\}$. $\square$

Example. The eigenvalues of the matrix $\begin{bmatrix} 3 & 6 & -8 \\ 0 & 0 & 6 \\ 0 & 0 & 2 \end{bmatrix}$ are 3, 0, and 2.

4 Vocabulary

Keywords from today's lecture:

1. **Linear functions.**

If U and V are vector spaces, then a function $f : U \rightarrow V$ is linear when

$$f(u + v) = f(u) + f(v) \quad \text{and} \quad f(cv) = cf(v)$$

for all $u, v \in U$ and $c \in \mathbb{R}$.

2. **Eigenvector** for an $n \times n$ matrix A .

A *nonzero* vector $v \in \mathbb{R}^n$ such that $Av = \lambda v$ for some real number $\lambda \in \mathbb{R}$.

The number λ is the **eigenvalue** of A for v .

$$\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \text{ is an eigenvector for } \begin{bmatrix} 0 & 2 & 0 \\ 2 & 0 & 0 \\ 0 & 0 & 2 \end{bmatrix} \text{ with eigenvalue } 2 \text{ as } \begin{bmatrix} 0 & 2 & 0 \\ 2 & 0 & 0 \\ 0 & 0 & 2 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 2 \\ 2 \\ 2 \end{bmatrix}.$$

3. **λ -eigenspace** for an $n \times n$ matrix A , where $\lambda \in \mathbb{R}$.

The subspace $\text{Nul}(A - \lambda I) \subseteq \mathbb{R}^n$ where I is the $n \times n$ identity matrix.

If λ is not an eigenvalue of A , then this subspace is $\{0\}$.

But if λ is an eigenvalue of A , then the subspace is nonzero.