

## 1 Review: Jordan decomposition

Let  $\mathbb{F}$  be an algebraically closed field, not necessarily with  $\text{char}(\mathbb{F}) = 0$ .

Let  $V$  be a finite-dimensional  $\mathbb{F}$ -vector space.

A linear map  $X \in \mathfrak{gl}(V)$  is *nilpotent* if  $X^n = 0$  for some  $n \gg 0$ .

A linear map  $X \in \mathfrak{gl}(V)$  is *semisimple* if it is *diagonalizable*.

Linear combinations of commuting semisimple operators are semisimple.

The restriction of a semisimple operator to any subspace that it preserves is also semisimple.

For each  $X \in \mathfrak{gl}(V)$ , there are unique elements  $X_{\text{ss}}, X_{\text{nil}} \in \mathfrak{gl}(V)$  such that

$$X_{\text{ss}} \text{ is semisimple, } X_{\text{nil}} \text{ is nilpotent, } X_{\text{ss}}X_{\text{nil}} = X_{\text{nil}}X_{\text{ss}}, \text{ and } \boxed{X = X_{\text{ss}} + X_{\text{nil}}}.$$

The boxed formula is called the *Jordan decomposition* of  $X$ .

In fact, both  $X_{\text{ss}}$  and  $X_{\text{nil}}$  are elements of  $\mathbb{F}\text{-span}\{X, X^2, X^3, \dots\}$ .

If  $X \in \mathfrak{gl}(V)$  is semisimple then  $X = X_{\text{ss}}$  and if  $X \in \mathfrak{gl}(V)$  is nilpotent then  $X = X_{\text{nil}}$ .

If  $X \in \mathfrak{gl}(V)$  has Jordan decomposition  $X = X_{\text{ss}} + X_{\text{nil}}$  then  $(\text{ad}_X)_{\text{ss}} = \text{ad}_{X_{\text{ss}}}$  and  $(\text{ad}_X)_{\text{nil}} = \text{ad}_{X_{\text{nil}}}$ .

Hence if  $X \in \mathfrak{gl}(V)$  is semisimple (respectively, nilpotent) then so is  $\text{ad}_X \in \mathfrak{gl}(\mathfrak{gl}(V))$ .

## 2 Cartan's criterion for solvability

We now assume (more strongly than above) that  $\mathbb{F}$  is an algebraically closed field with  $\text{char}(\mathbb{F}) = 0$ .

Let  $V$  be an  $\mathbb{F}$ -vector space with  $\dim(V) < \infty$

Our first goal today is to prove a simple condition that implies that a Lie subalgebra of  $\mathfrak{gl}(V)$  is solvable.

**Lemma.** Let  $A \subseteq B$  be two subspaces of  $\mathfrak{gl}(V)$ . Define

$$M = \{Y \in \mathfrak{gl}(V) : [Y, B] \subseteq A\}$$

and suppose  $X \in M$  has  $\text{trace}(XY) = 0$  for all  $Y \in M$ . Then  $X$  is nilpotent.

*Proof.* One way to prove the lemma is by the following clever argument.

Write the Jordan decomposition of  $X$  as  $X = X_{\text{ss}} + X_{\text{nil}}$ .

Let  $v_1, v_2, \dots, v_n$  be a basis for  $V$  in which the matrix of  $X$  is in Jordan canonical form.

Then the matrices of  $X_{\text{ss}}$  and  $X_{\text{nil}}$  in this basis are respectively diagonal and strictly upper-triangular.

In particular we can write  $X_{\text{ss}}v_i = a_i v_i$  for some eigenvalues  $a_i \in \mathbb{F}$ .

Because  $\text{char}(\mathbb{F}) = 0$ , we can define  $E = \mathbb{Q}\text{-span}\{a_1, a_2, \dots, a_n\} \subseteq \mathbb{F}$ .

We want to show that  $X_{\text{ss}} = 0$  as then  $X = X_{\text{nil}}$  is nilpotent.

This holds if and only if  $a_1 = a_2 = \dots = a_n = 0$ , meaning that  $E = 0$ .

Let  $E^*$  be the  $\mathbb{Q}$ -vector space of  $\mathbb{Q}$ -linear maps  $E \rightarrow \mathbb{Q}$ .

Since  $\dim_{\mathbb{Q}}(E) \leq n < \infty$  it holds that  $\dim_{\mathbb{Q}}(E^*) = \dim_{\mathbb{Q}}(E)$  and it suffices to show that  $E^* = 0$ .

Suppose  $f \in E^*$ . To prove that  $E^* = 0$  we will show that  $f = 0$ .

Let  $Y \in \mathfrak{gl}(V)$  be the linear map with  $Yv_i = f(a_i)v_i$  for all  $i$ .

Let  $e_{ij} \in \mathfrak{gl}(V)$  be the linear map that sends  $v_k \mapsto \delta_{jk}v_i$  where  $\delta_{jk} = |\{j\} \cap \{k\}|$ .

As in the last lecture, one can check that  $\text{ad}_{X_{\text{ss}}} e_{ij} = (a_i - a_j)e_{ij}$  and  $\text{ad}_Y e_{ij} = (f(a_i) - f(a_j))e_{ij}$ .

It is a standard result in polynomial interpolation that some  $r(x) \in \mathbb{Q}[x]$  exists with

$$r(a_i - a_j) = f(a_i) - f(a_j) = f(a_i - a_j) \quad \text{for all } 1 \leq i, j \leq n.$$

(Look up *Lagrange polynomials* to see an explicit construction.)

Since  $r(0) = r(a_i - a_i) = f(a_i - a_i) = f(0) = 0$  we have  $r(x) \in x\mathbb{Q}[x]$ .

We have  $\text{ad}_Y = r(\text{ad}_{X_{\text{ss}}})$  since both sides give the same result when applied to each  $e_{ij}$ .

Since  $\text{ad}_{X_{\text{ss}}} = (\text{ad}_X)_s$  we also have  $\text{ad}_{X_{\text{ss}}} = p(\text{ad}_X)$  for some polynomial  $p(x) \in x\mathbb{F}[x]$ .

Since we assume  $X \in M$  it follows that  $\text{ad}_X(B) \subseteq A$  so

$$[Y, B] = \text{ad}_Y(B) = r(\text{ad}_{X_{\text{ss}}})(B) = r(p(\text{ad}_X))(B) \subseteq A.$$

This implies that  $Y \in M$ . Therefore our hypotheses assert that  $\text{trace}(XY) = 0$ .

But the matrices of  $X_{\text{ss}}$  and  $Y$  are diagonal in the basis  $v_1, v_2, \dots, v_n$  while  $X_{\text{nil}}$  is strictly upper-triangular.

Hence the matrix of  $X_{\text{nil}}Y$  is also strictly upper triangular so

$$0 = \text{trace}(XY) = \text{trace}(X_{\text{ss}}Y) + \text{trace}(X_{\text{nil}}Y) = \text{trace}(X_{\text{ss}}Y) = \sum_{i=1}^n a_i f(a_i) \in E.$$

Thus  $0 = f(0) = f(\text{trace}(XY)) = \sum_{i=1}^n f(a_i)^2 \in \mathbb{Q}$  which can only hold if  $f = 0$ , as needed.  $\square$

The next proposition is much easier to prove.

**Proposition.** If  $X, Y, Z \in \mathfrak{gl}(V)$  then  $\text{trace}([X, Y]Z) = \text{trace}(X[Y, Z])$ .

*Proof.* The two traces expand to  $\text{trace}(XYZ) - \text{trace}(YXZ)$  and  $\text{trace}(XYZ) - \text{trace}(XZY)$ .

The general identity  $\text{trace}(AB) = \text{trace}(BA)$  implies that  $\text{trace}(YXZ) = \text{trace}(XZY)$ .  $\square$

The previous results lead to the following theorem.

**Theorem** (Cartan's criterion). Let  $L \subseteq \mathfrak{gl}(V)$  be a Lie algebra where  $\dim(V) < \infty$ .

Suppose  $\text{trace}(XY) = 0$  for all  $X \in [L, L]$  and  $Y \in L$ . Then  $L$  is solvable.

*Proof.* To show that  $L$  is solvable it suffices to check that  $[L, L]$  is nilpotent.

For this, will show that every  $X \in [L, L]$  is a nilpotent element of  $\mathfrak{gl}(V)$ .

This will imply that every element of  $[L, L]$  is  $\text{ad}$ -nilpotent.

Then Engel's theorem tells us that  $[L, L]$  is nilpotent.

Let  $M = \{Y \in \mathfrak{gl}(V) : [Y, L] \subseteq [L, L]\}$ .

We have  $[L, L] \subseteq L \subseteq M$  but  $M$  might be strictly larger than  $L$ .

If  $X_1, X_2 \in L$  and  $Y \in \mathfrak{gl}(V)$  are any elements then by the previous proposition

$$\text{trace}([X_1, X_2]Y) = \text{trace}(X_1[X_2, Y]) = \text{trace}([X_2, Y]X_1) = -\text{trace}([Y, X_2]X_1).$$

By definition, if  $Y \in M$  then  $[Y, X_2] \in [L, L]$  and then by hypothesis  $\text{trace}([Y, X_2]X_1) = 0$ .

Hence if  $X_1, X_2 \in L$  and  $Y \in M$  then  $\text{trace}([X_1, X_2]Y) = 0$ .

But if  $X \in [L, L]$ , then  $X$  is a linear combination of brackets  $[X_1, X_2]$  so  $\text{trace}(XY) = 0$  for all  $Y \in M$ .

We conclude by the lemma (with  $A = [L, L]$  and  $B = L$ ) that every  $X \in [L, L]$  is nilpotent, as needed.  $\square$

### 3 Killing form

Let  $L$  be a finite-dimensional Lie algebra.

**Definition.** The *Killing form* of  $L$  is the bilinear form  $\mathcal{K} : L \times L \rightarrow L$  defined by

$$\mathcal{K}(X, Y) = \text{trace}(\text{ad}_X \text{ad}_Y) \quad \text{for } X, Y \in L.$$

To compute  $\mathcal{K}(X, Y)$ , pick a basis for  $L$  and then write down the matrices of  $\text{ad}_X$  and  $\text{ad}_Y$  in this basis.

Then multiply the matrices of  $\text{ad}_X$  and  $\text{ad}_Y$  and sum the diagonal entries in the product

We mention two easy properties of the Killing form:

**Proposition.** The Killing form is *symmetric* in the sense that  $\mathcal{K}(X, Y) = \mathcal{K}(Y, X)$  for all  $X, Y \in L$ .

The Killing form is also *associative* in the sense that  $\mathcal{K}([X, Y], Z) = \mathcal{K}(X, [Y, Z])$  for all  $X, Y, Z \in L$ .

The second property is equivalent to a result proved earlier today.

**Example.** Let us compute the Killing form when  $L = \mathfrak{sl}_2(\mathbb{F}) = \mathbb{F}\text{-span}\{E, H, F\}$  for

$$E = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \quad H = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}, \quad \text{and} \quad F = \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}.$$

Check that  $[E, E] = [H, H] = [F, F] = 0$  and  $[E, H] = -2E$  and  $[F, H] = 2F$  and  $[E, F] = H$ .

Relative to the ordered basis  $E, H, F$ , we therefore have

$$\text{ad}_E = \begin{bmatrix} 0 & -2 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}, \quad \text{ad}_H = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -2 \end{bmatrix}, \quad \text{and} \quad \text{ad}_F = \begin{bmatrix} 0 & 0 & 0 \\ -1 & 0 & 0 \\ 0 & 2 & 0 \end{bmatrix}.$$

This lets us compute

$$\begin{bmatrix} \mathcal{K}(E, E) & \mathcal{K}(E, H) & \mathcal{K}(E, F) \\ \mathcal{K}(H, E) & \mathcal{K}(H, H) & \mathcal{K}(H, F) \\ \mathcal{K}(F, E) & \mathcal{K}(F, H) & \mathcal{K}(F, F) \end{bmatrix} = \begin{bmatrix} 0 & 0 & 4 \\ 0 & 8 & 0 \\ 4 & 0 & 0 \end{bmatrix}.$$

The *radical* of  $\mathcal{K} : L \times L \rightarrow L$  (or more generally of any symmetric bilinear form) is the subspace

$$\text{Rad}(\mathcal{K}) = \{X \in L : \mathcal{K}(X, Y) = 0 \text{ for all } Y \in L\} = \{Y \in L : \mathcal{K}(X, Y) = 0 \text{ for all } X \in L\}.$$

The form  $\mathcal{K}$  is *non-degenerate* if  $\text{Rad}(\mathcal{K}) = 0$ .

We have  $\text{Rad}(\mathcal{K}) = 0$  precisely when the map  $\mathcal{K}(X, \cdot) : L \rightarrow L$  is zero if and only if  $X = 0$ .

Less obviously, if  $X_1, X_2, \dots, X_n$  is any basis for  $L$  then:

**Proposition.** We have  $\text{Rad}(\mathcal{K}) = 0$  if and only if the  $n \times n$  matrix  $[\mathcal{K}(X_i, X_j)]_{1 \leq i, j \leq n}$  is invertible.

*Proof.* If  $M$  denotes this matrix and  $Y = \sum_{i=1}^n a_i X_i$  and  $Z = \sum_{i=1}^n b_i X_i$  for some  $a_i, b_i \in \mathbb{F}$ , then

$$\mathcal{K}(Y, Z) = a^\top M b \quad \text{for the vectors } a = \begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_n \end{bmatrix} \text{ and } b = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{bmatrix}.$$

If  $M$  is invertible and  $b \neq 0$  then  $Mb \neq 0$  so  $\mathcal{K}(Y, Z) \neq 0$  when we take  $a = Mb$ .

Thus if  $M$  is invertible then  $\mathcal{K}(Y, Z)$  for all  $Y \in L$  only when  $Z = 0$ , so  $\text{Rad}(\mathcal{K}) = 0$ .

Conversely, if  $M$  is not invertible then some nonzero  $b$  has  $Mb = 0$ .

In this case the corresponding nonzero  $Z \in L$  belongs to  $\text{Rad}(\mathcal{K})$ . □

We see from this proposition that the Killing form for  $\mathfrak{sl}_2(\mathbb{F})$  is non-degenerate if and only if  $\text{char}(\mathbb{F}) \neq 2$ .

**Proposition.** Let  $I \subseteq L$  be an ideal.

Then the Killing form  $\mathcal{K}_I$  of  $I$  is the restriction of the Killing form  $\mathcal{K} = \mathcal{K}_L$  of  $L$ .

*Proof.* If  $\phi : V \rightarrow W \subseteq V$  is a linear map where  $W$  and  $V$  are finite-dimensional vector spaces, then

$$\text{trace}(\phi) = \text{trace}(\phi|_W)$$

since if  $w_1, w_2, \dots, w_k$  is a basis for  $W$  and  $w_{k+1}, w_{k+1}, \dots, w_n$  extends this to a basis of  $V$  then the corresponding matrix of  $\phi$  has the block diagonal form

$$\left[ \begin{array}{c|c} A & * \\ \hline 0 & 0 \end{array} \right]$$

where  $A$  is the matrix of  $\phi|_W$  in the basis  $w_1, w_2, \dots, w_k$ .

Now apply this observation with  $V = L$  and  $W = I$  and  $\phi = \text{ad}_X \text{ad}_Y$ . □

Recall that  $L$  is *semisimple* if it has no nonzero solvable ideals, or equivalently if  $\text{Rad}(L) = 0$ .

**Theorem.** A finite-dimensional Lie algebra is semisimple if and only if its Killing form is non-degenerate. Equivalently, when  $\dim(L) < \infty$  we have  $\text{Rad}(L) = 0$  if and only if  $\text{Rad}(\mathcal{K}) = 0$ .

*Proof.* Let  $S = \text{Rad}(\mathcal{K})$ . The associativity of the Killing form implies that  $S$  is an ideal of  $L$ .

In fact, Cartan's criterion implies that  $\text{ad}(S)$  is a solvable ideal of  $\mathfrak{gl}(L)$ , since

$$\text{trace}(\text{ad}_X \text{ad}_Y) = \mathcal{K}(X, Y) = 0 \quad \text{for all } X \in S \supseteq [S, S] \text{ and all } Y \in L \supseteq S.$$

The center  $Z(L)$  is abelian and hence solvable, and contained in  $S$ , so  $\text{ad}(S) \cong S/Z(L)$  is also solvable.

Thus if the largest solvable ideal  $\text{Rad}(L) = 0$  is zero then we also have  $S = 0$ .

Now suppose conversely that  $S = 0$ . We want to show that  $\text{Rad}(L) = 0$ .

Assume  $I \subseteq L$  is an abelian ideal. It suffices to check that  $I \subseteq S$  (which means that  $I = 0$  when  $S = 0$ ).

This is because if  $\text{Rad}(L)$  is nonzero then  $\text{Rad}(L)^{(n)}$  is a nonzero abelian ideal for some  $n \geq 1$ .

Let  $X \in I$  and  $Y \in L$ . Then  $\text{ad}_X \text{ad}_Y$  is a map  $L \rightarrow I$  and  $(\text{ad}_X \text{ad}_Y)^2$  is a map  $L \rightarrow [I, I] = 0$ .

Thus  $\text{ad}_X \text{ad}_Y$  is nilpotent so its eigenvalues are all 0, so its trace (the sum of the eigenvalues) is also 0.

This shows that  $\mathcal{K}(X, Y) = 0$  for all  $X \in I$  and  $Y \in L$ , which means that  $I \subseteq S$  as needed.  $\square$