

Examples	Example 1
Example Indicate which condition in the definition is violated for each matrix. State the row operation required to transform the matrix into reduced form. (a) $\begin{bmatrix} 0 & 1 & & -2 \\ 1 & 0 & & 3 \end{bmatrix}$ Ans: 4 $(R_1 \leftrightarrow R_2)$ (b) $\begin{bmatrix} 1 & 2 & -2 & & 3 \\ 0 & 0 & 1 & & -1 \end{bmatrix}$ Ans: 3 $(R_1 + 2R_2 \rightarrow R_1)$ (c) $\begin{bmatrix} 1 & 0 & & -3 \\ 0 & 0 & & 0 \\ 0 & 1 & & -2 \end{bmatrix}$ Ans: 1 $(R_2 \leftrightarrow R_3)$ (d) $\begin{bmatrix} 1 & 0 & 0 & & -1 \\ 0 & 2 & 0 & & 3 \\ 0 & 0 & 1 & & -5 \end{bmatrix}$ Ans: 2 $(\frac{1}{2}R_2 \rightarrow R_2)$	Solving system of linear equations: Example Solve $\begin{cases} 3x_1 + 8x_2 - x_3 &= -18 \\ 2x_1 + x_2 + 5x_3 &= 8 \\ 2x_1 + 4x_2 + 2x_3 &= -4 \end{cases}$
L	シンク・ヨー・ビー・ペロ・ペロ・ペロ・ペロ・ペロ・ペロ・ペート・シング
Maosheng Xiong Department of Mathematics, HKUS1 MATH 1003 Calculus and Linear Algebra (Lecture 7)	Maosheng Xiong Department of Mathematics, HKUS1 MATH 1003 Calculus and Linear Algebra (Lecture 7)
Examples	Examples
Example 1 - Solution Part 1	Example 1 - Solution Part 2

Maosheng Xiong Department of Mathematics, HKUST MATH 1003 Calculus and Linear Algebra (Lecture 7)

Maosheng Xiong Department of Mathematics, HKUST MATH 1003 Calculus and Linear Algebra (Lecture 7)

Examples	Examples
Example 1 - Solution Part 3	Example 2
Therefore, from the reduced form, we can easily obtain the solution to the linear system: $\begin{cases} x_1 = 0 \\ x_2 = -2 \\ x_3 = 2 \end{cases}$	Example Solve $\begin{cases} 2x_1 - x_2 - 3x_3 &= 8\\ x_1 - 2x_2 &= 7 \end{cases}$
< ロ > 〈 国 > 〈 三 > 〈 三 > 〈 三 > 〈 三 > 〈 三 > 〈 三 > 〈 三 > 〈 三 > 〈 三 > 〈 三 > 〈 三 > 〉 へぐ	< ロ > < 雪 > < 差 > く 差 - つくぐ
Maosheng Xiong Department of Mathematics, HKUST MATH 1003 Calculus and Linear Algebra (Lecture 7)	Maosheng Xiong Department of Mathematics, HKUST MATH 1003 Calculus and Linear Algebra (Lecture 7)
Examples 2 - Solution	Examples 2 - Infinite Number of Solutions
$\begin{bmatrix} 2 & -1 & -3 & & 8 \\ 1 & -2 & 0 & & 7 \end{bmatrix} \xrightarrow{R_1 \leftrightarrow R_2} \begin{bmatrix} 1 & -2 & 0 & & 7 \\ 2 & -1 & -3 & & 8 \end{bmatrix}$ $(-2)R_1 + R_2 \rightarrow R_2 \begin{bmatrix} 1 & -2 & 0 & & 7 \\ 0 & 3 & -3 & & -6 \end{bmatrix} \xrightarrow{\frac{1}{3}R_2 \rightarrow R_2} \begin{bmatrix} 1 & -2 & 0 & & 7 \\ 0 & 1 & -1 & & -2 \end{bmatrix}$ $2R_2 + R_1 \rightarrow R_1 \begin{bmatrix} 1 & 0 & -2 & & 3 \\ 0 & 1 & -1 & & -2 \end{bmatrix}$	The linear system corresponding to the reduced form is $\begin{cases} x_1 & -2x_3 &= 3 \\ x_2 & -x_3 &= -2 \end{cases}$ Now we classify the variables of the system into two types: • Non-free variables: Variables corresponding to the columns that contain the leftmost 1's (x_1, x_2) • Free variables: The remaining variables (x_3)

Maosheng Xiong Department of Mathematics, HKUST MATH 1003 Calculus and Linear Algebra (Lecture 7)

Maosheng Xiong Department of Mathematics, HKUST MATH 1003 Calculus and Linear Algebra (Lecture 7)

